

Learning gLMPPM - generalized LMPPM

Peter Vojtas

Content

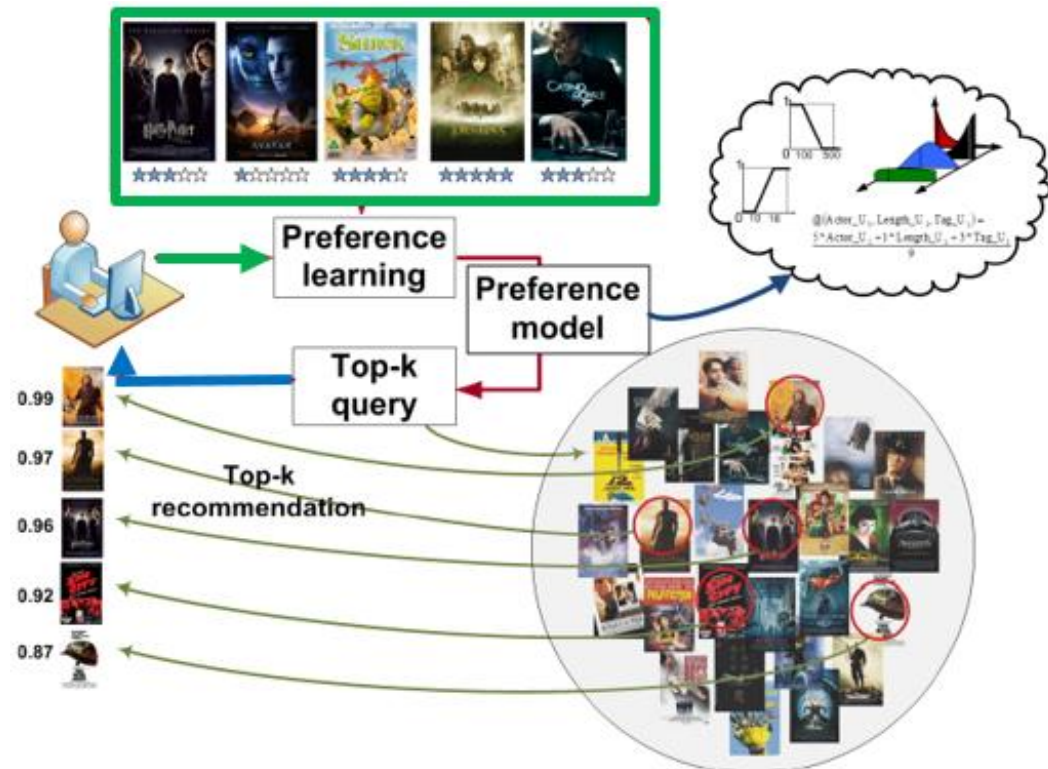
- We have **extended the portfolio of models** in hope some of them will fit to user's behavior. Let's try to find methods to learn from data generated by respective models
- There was some learning of LMPM preferences in NSW166 – **specific** methods under specific circumstances of data distribution, **here** we learn gLMPM models, still based on a method finding ideal points and methods finding aggregation or at least PC contour lines
- Our experiments involve:
 - Experiment 1. LMPM learning, more general data distribution, hill/valley attribute preferences
 - Experiment 2. Data generated by product disjunction on respective PC contour lines
 - Experiment 3. Data generated by product conjunction on respective PC contour lines
 - Experiment 4. Arbitrary Pareto compliant contour lines



User's preference learning

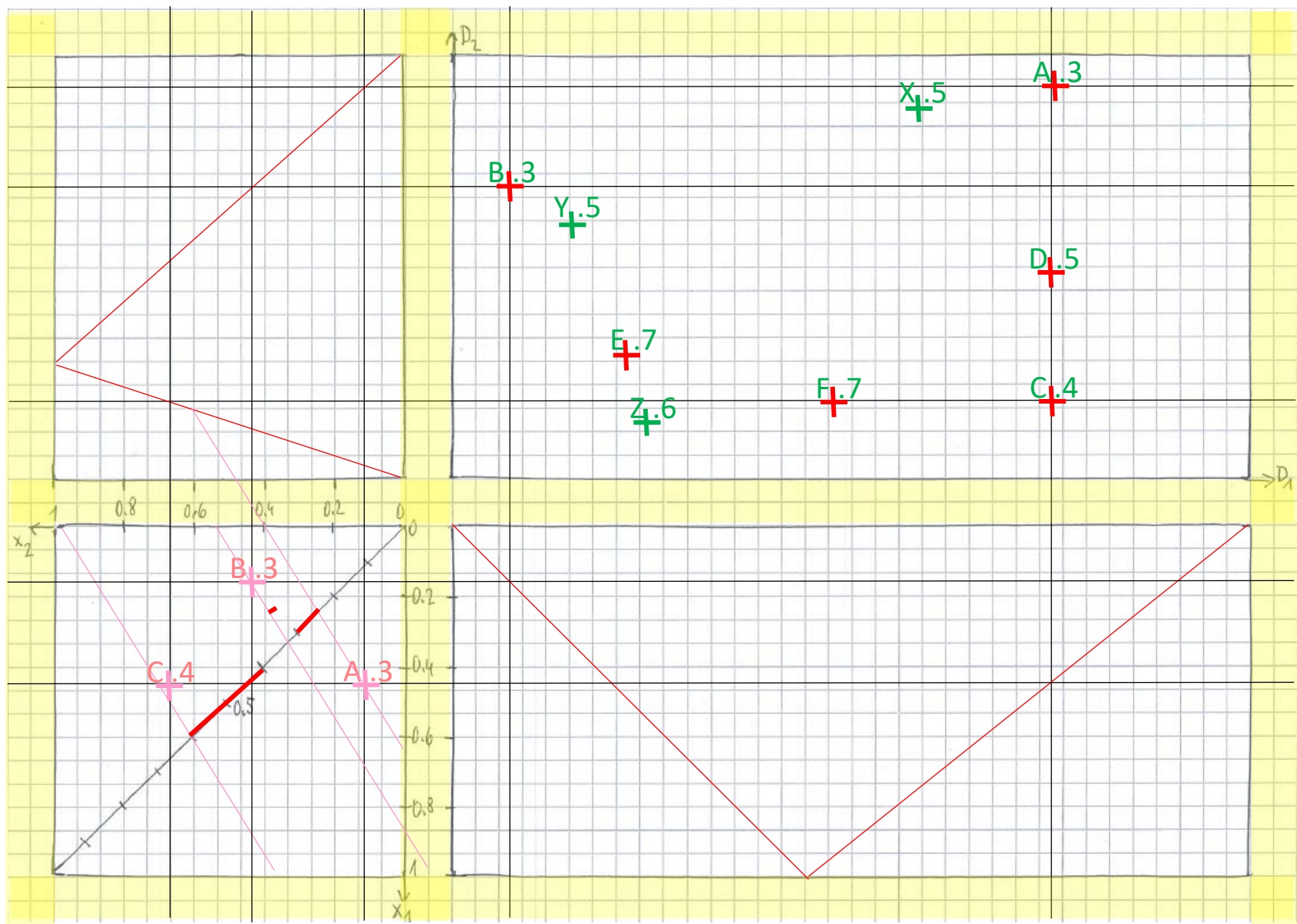
- We have
 - User behavior

- Would like to have an
 - gLMPM user model to compute top-k for recommendation
- Can we make this recommendation visual? Human intuitive?



Learning from NSWI166, go to slides 3-40

C1 TEST
M2 A2



- A.3
- B.3
- C.4
- D.5
- E.7
- F.7
- X.5
- Y.5
- Z.6

Experiment 1.

LMPM learning, more general data distribution, hill/valley attribute preferences

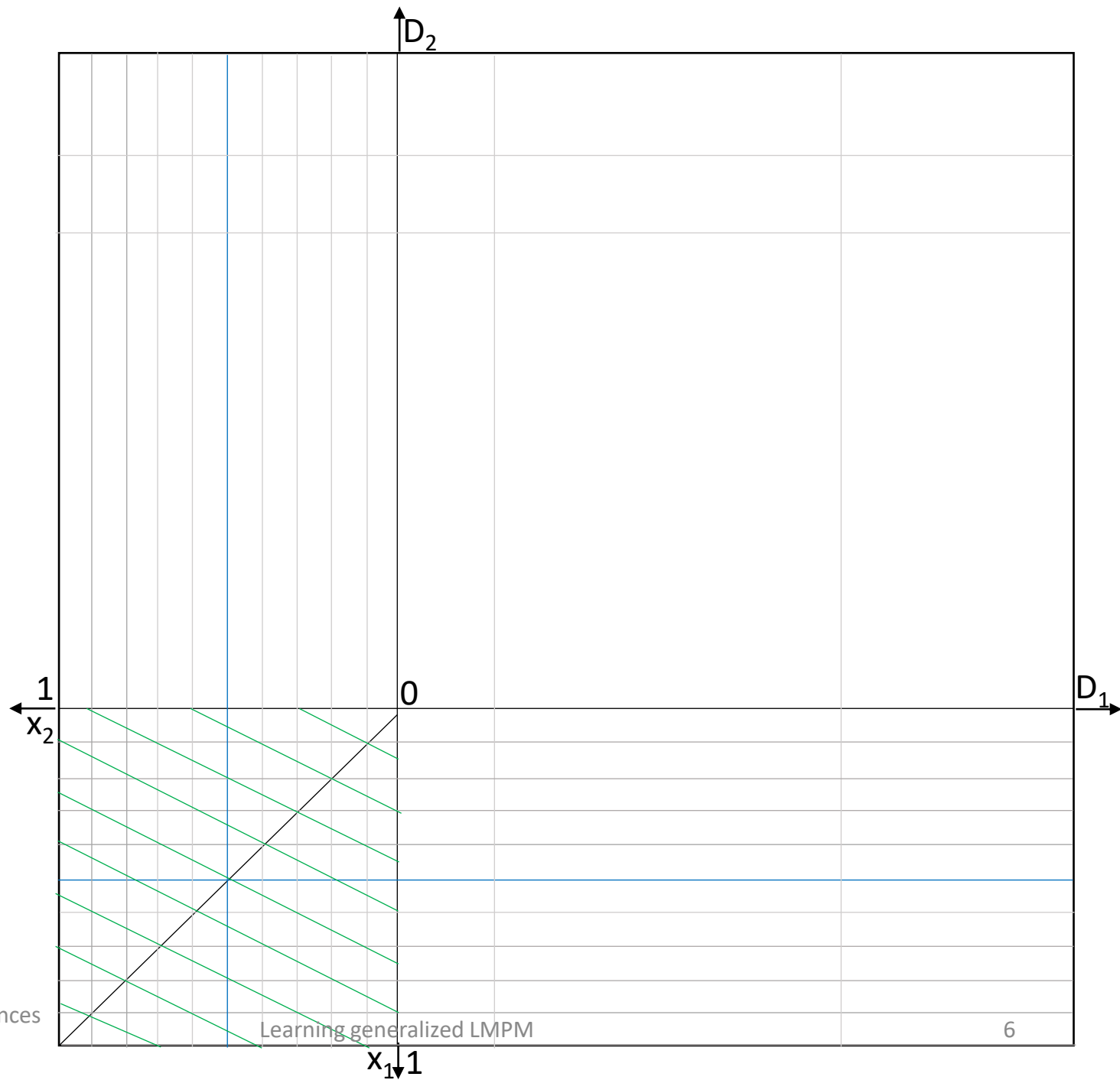
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Ex.1 can be hill – valley

We would like to generate data in such a way that learning aggr. needs a new method

There will be no data with same preference

Choose aggr.
 $(2x_1 + x_2)/3$

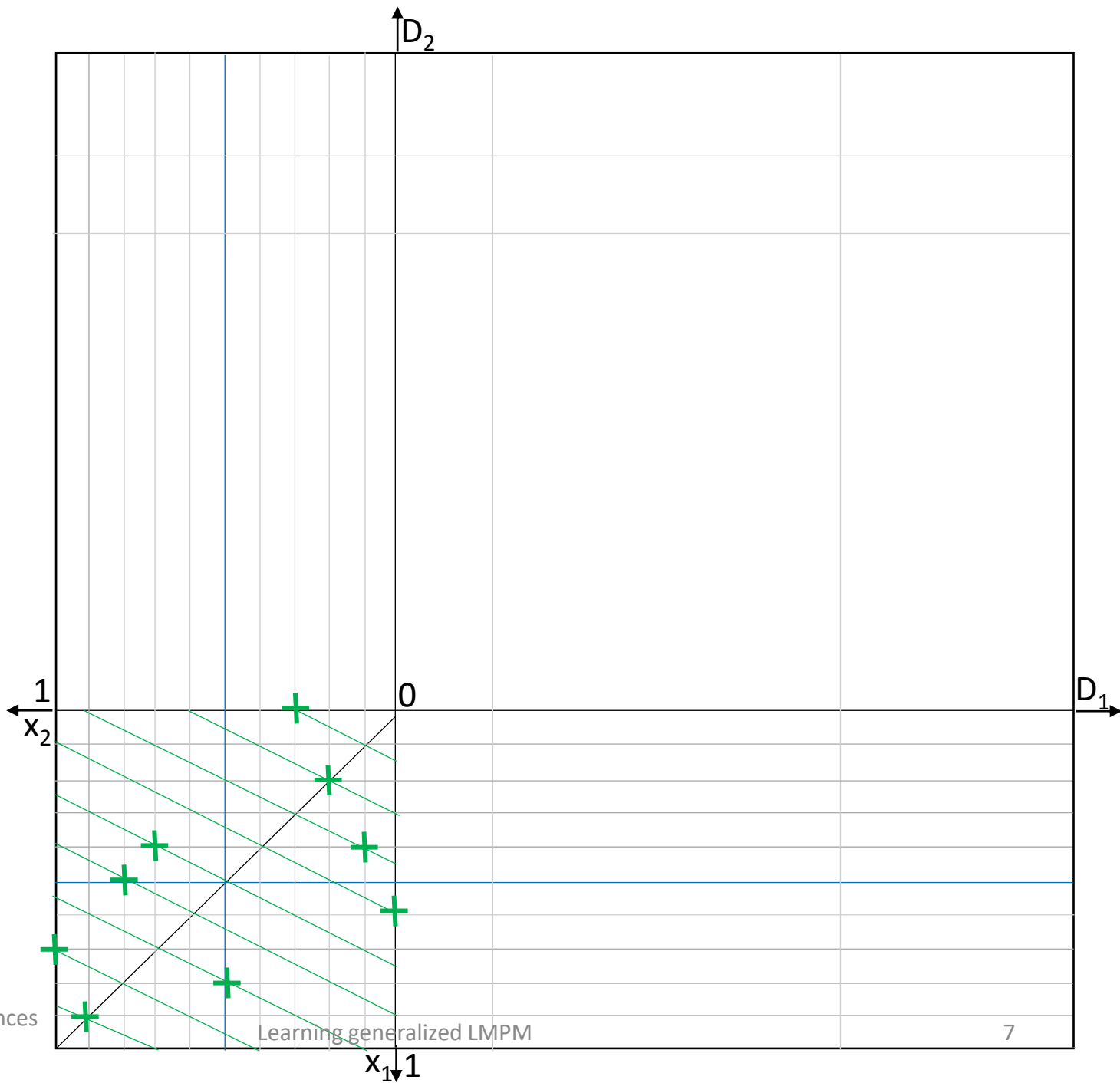


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Ex.1 can be hill – valley , new @ methods needed

Draw all decimal valued contour lines of $(2x_1 + x_2)/3$
And chose one point on each.

Only for copying

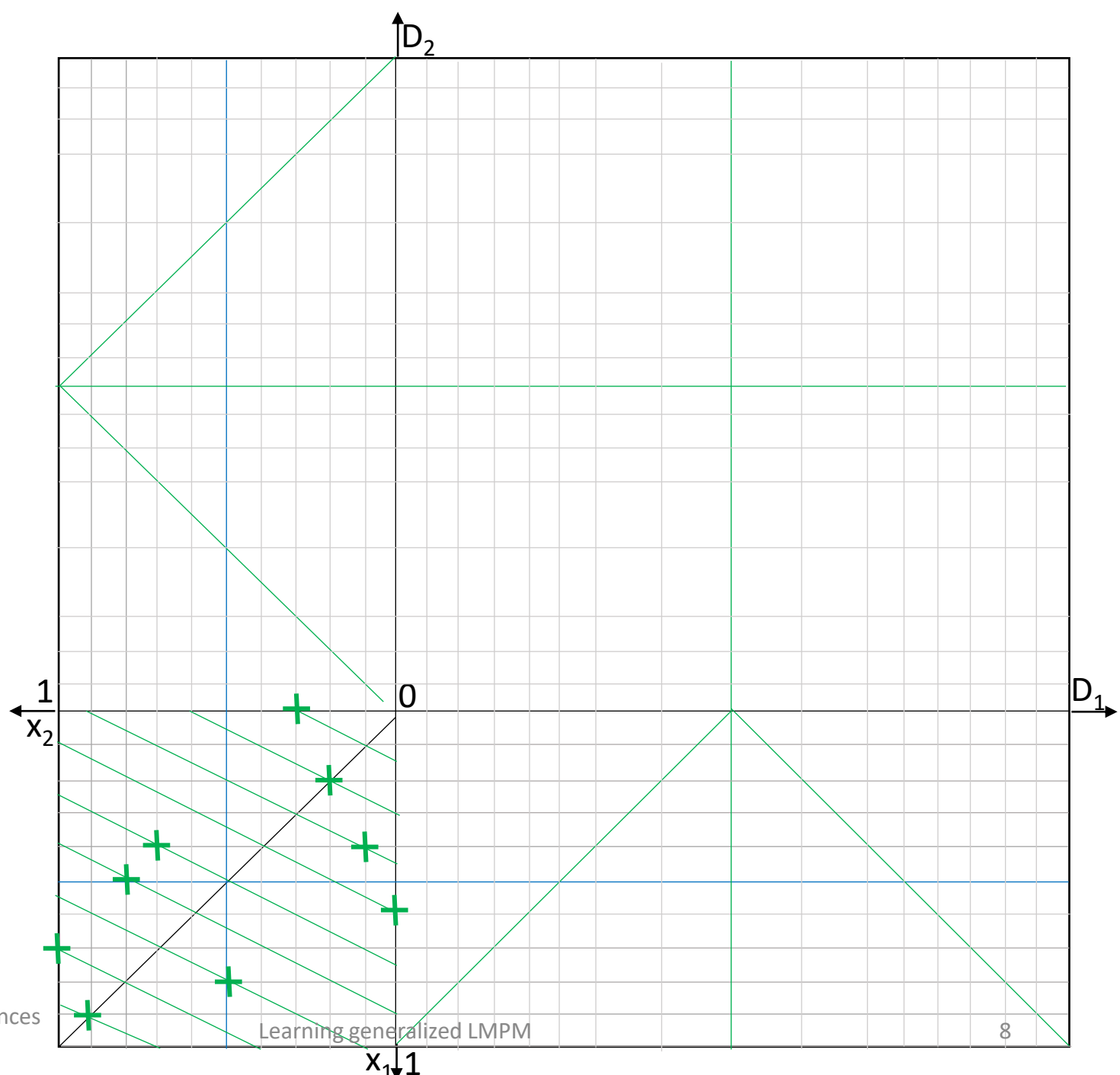


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Ex.1 can be hill – valley , new @ methods needed

We have decimal valued contour lines of $(2x_1 + x_2)/3$ points on each.

Chose attr. prefs. hill/valley



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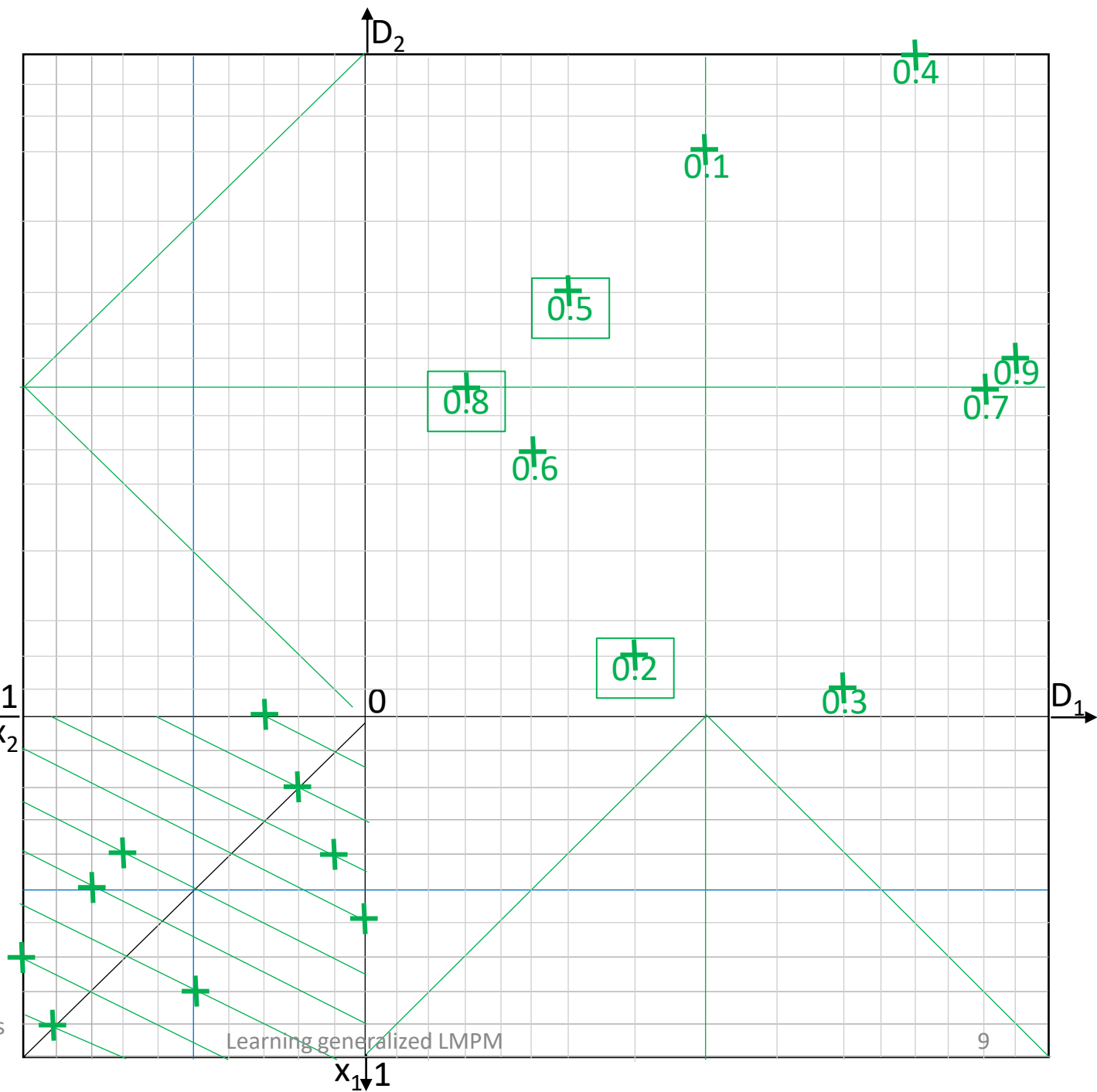
Ex.1 can be hill – valley , new @ methods needed

We have decimal valued contour lines of $(2x_1 + x_2)/3$ points on each. and attr. prefs.

Each point has four coimages in DC – chose one possibility rotating choice in quadrants (this can be changed in future data set generation).

Pref.score is also ID

Fix also train/ test set.



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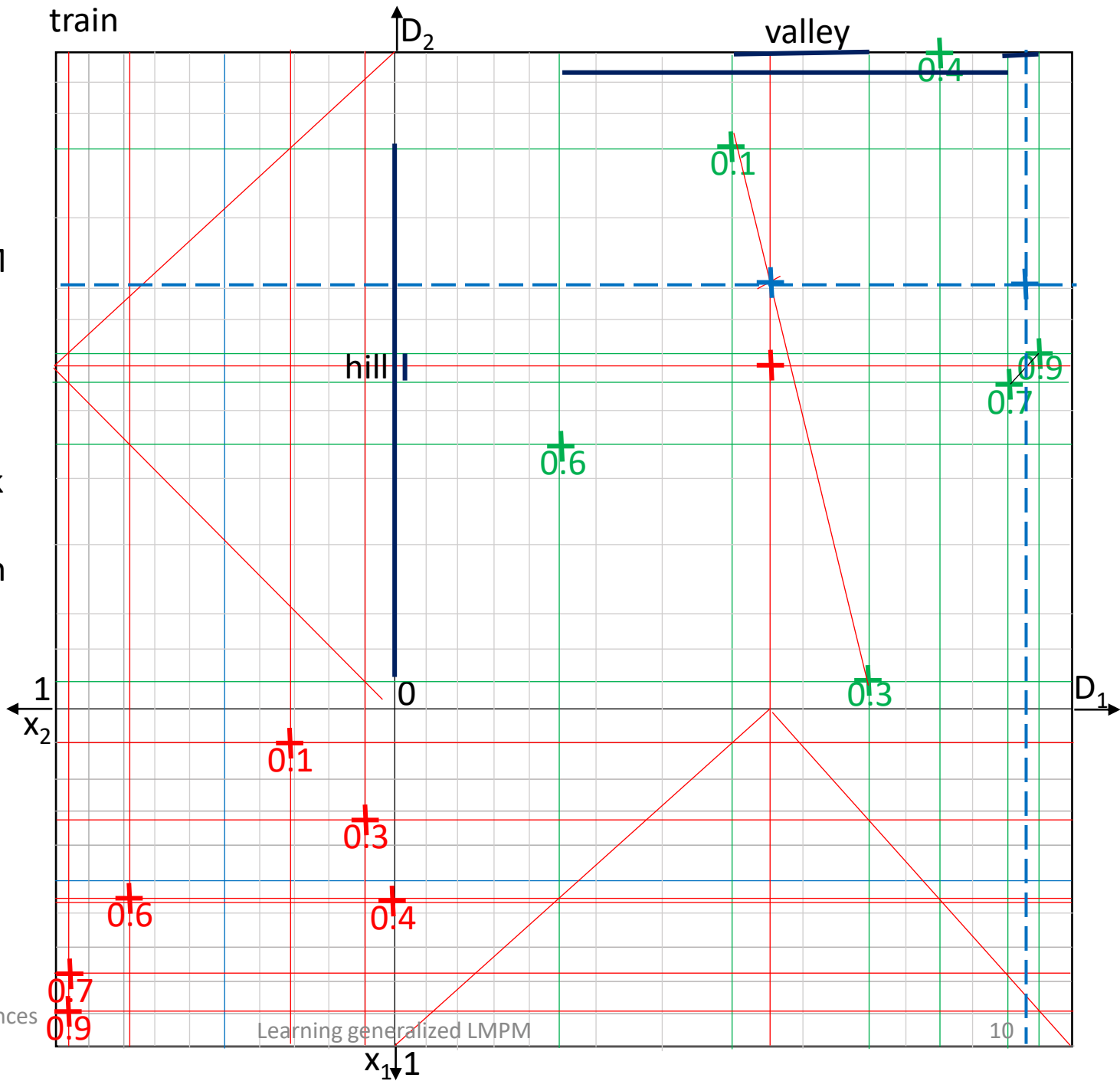
Ex.1 method i1
First decide hill / valley – projection smaller / bigger.

To learn an LMPM model, first a method i1 for atr.prefs.

We find four candidates for peak / valley points by center of mass (min and max pairs). Chose a red one, more regularly dividing train set

Find candidates in PC

train



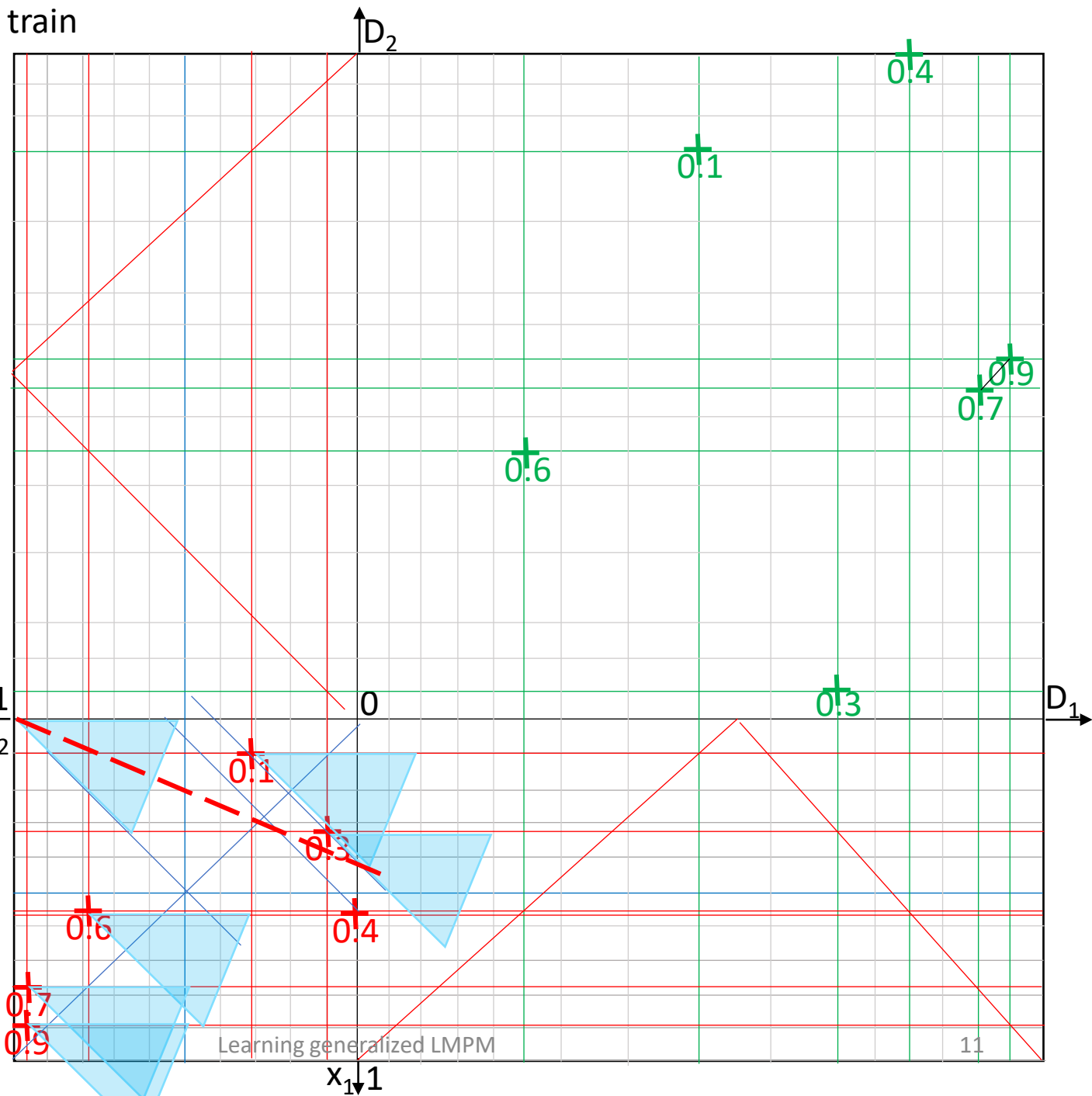
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Ex.1.1 method i1.

a1. Learning gives attr. prefs and training set images in PC. Points are Pareto compliant

Let's first try to find a max NW-SE angle for all train points preserves Pareto (0.1 to 0.3)

Angle method **a1**:
Let's chose angle
axis as our guess for aggregation



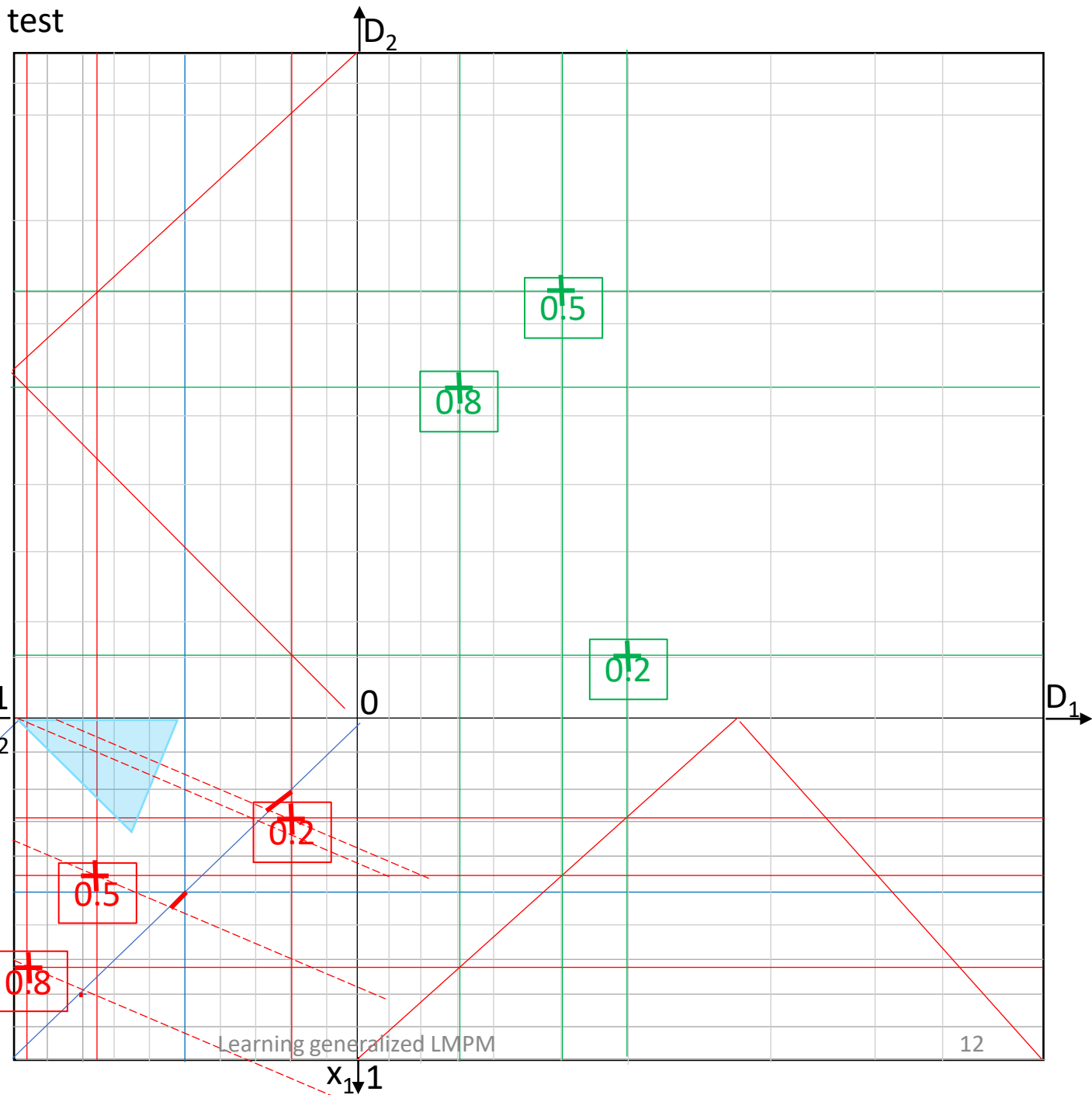
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Ex.1.1 method i1a1.

We have an estimation of atr.prefs. and aggregation, hence a model m1.i1.a1

Using m1.i1.a1 find images of test set

Let's calculate error (graphically)

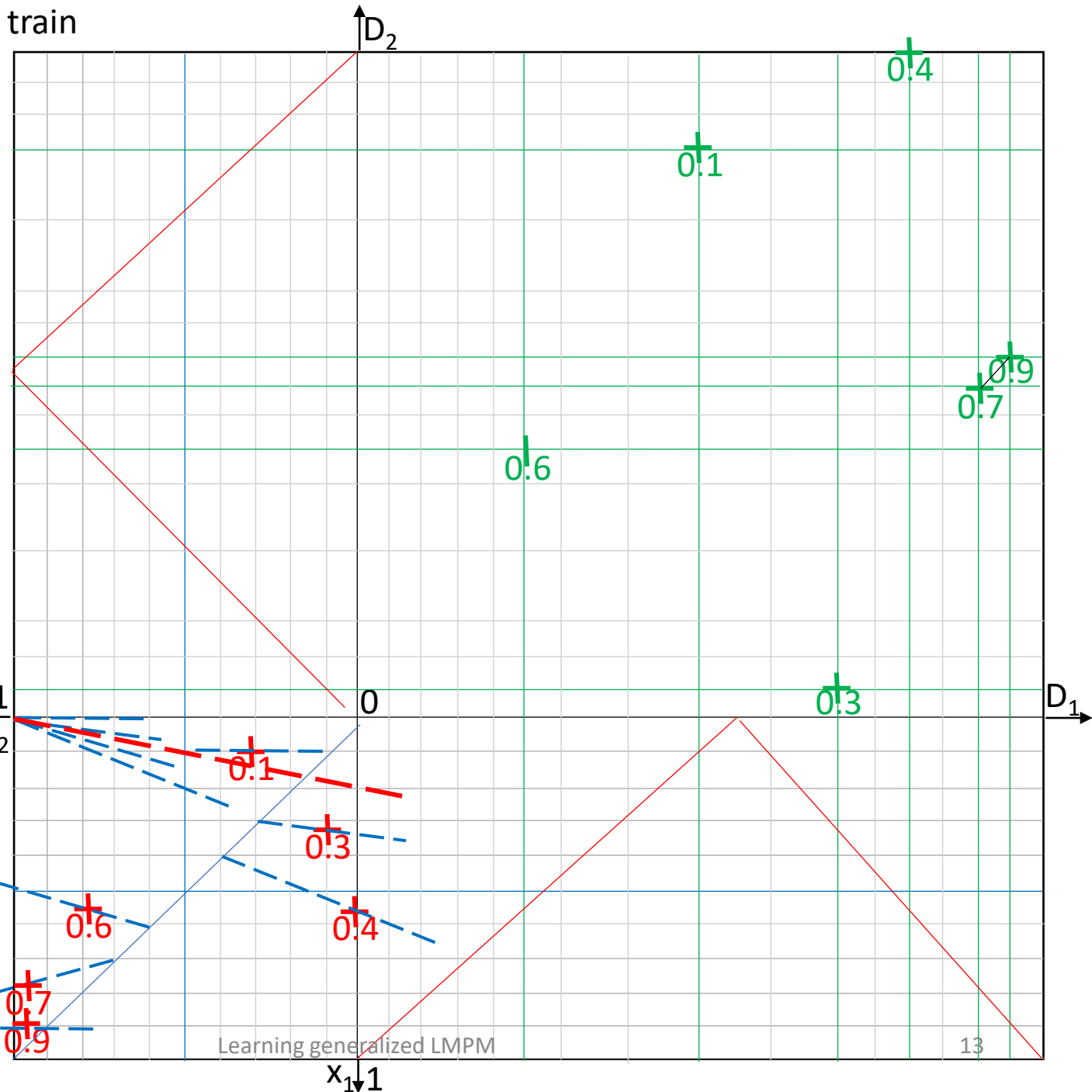


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Ex.1.2 method i1a2.

Learning gives attr. prefs and training set images in PC by i1. **a2 method:** construct an **angle of connections point with "it's" value on the diagonal** – and get the angle axis.

Expected directions NW-SE, violated by 0.7 – confidence 5/6. Lines create an angle (much smaller than previous one), chose again an axis

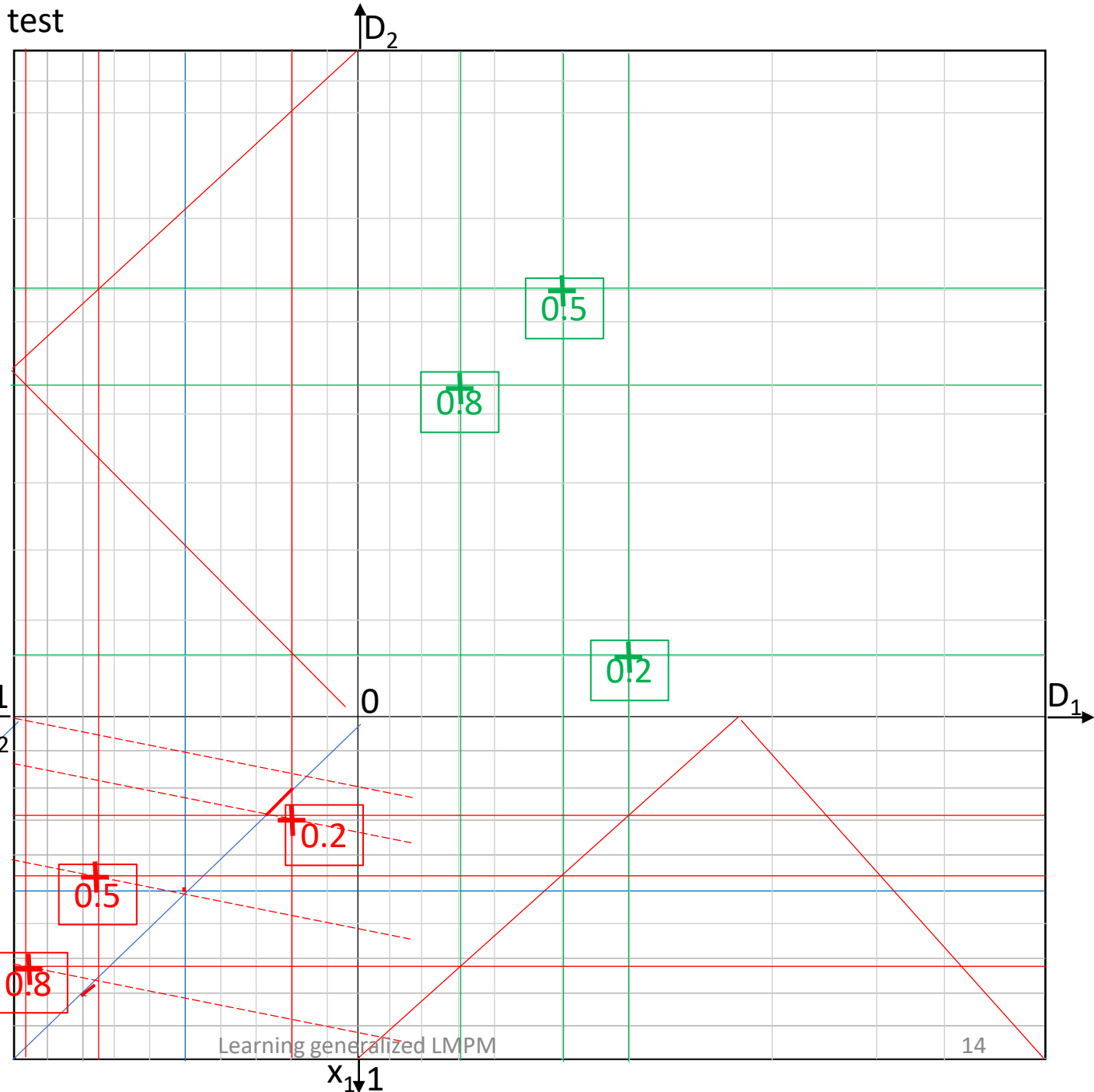


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Ex.1.2 method 2. Error on test set

Second angle axis
method as our
guess for
aggregation

Clean data, remain
necessary for test
set and calculate
error (graphically)



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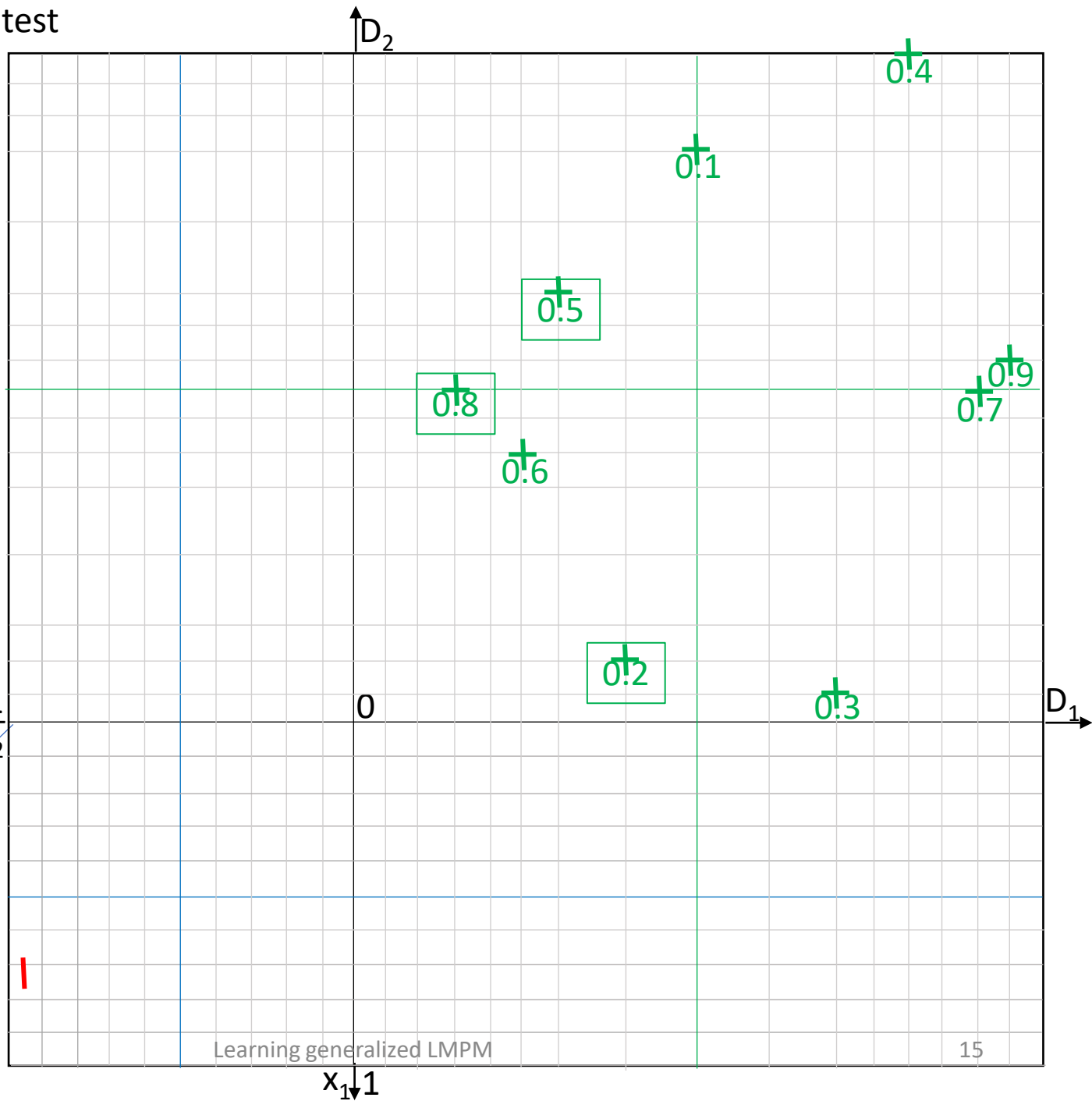
Example 1 résumé

attr. pref. easy as
we know triangles
over whole domain

We know @ are
weighted average,
two methods for @

Both "angle" quite
good, second a
little better

test



$\frac{1}{x_2}$

$i1a2$

$i1a1$

Experiment 2.

Data generated by product disjunction
on respective PC contour lines

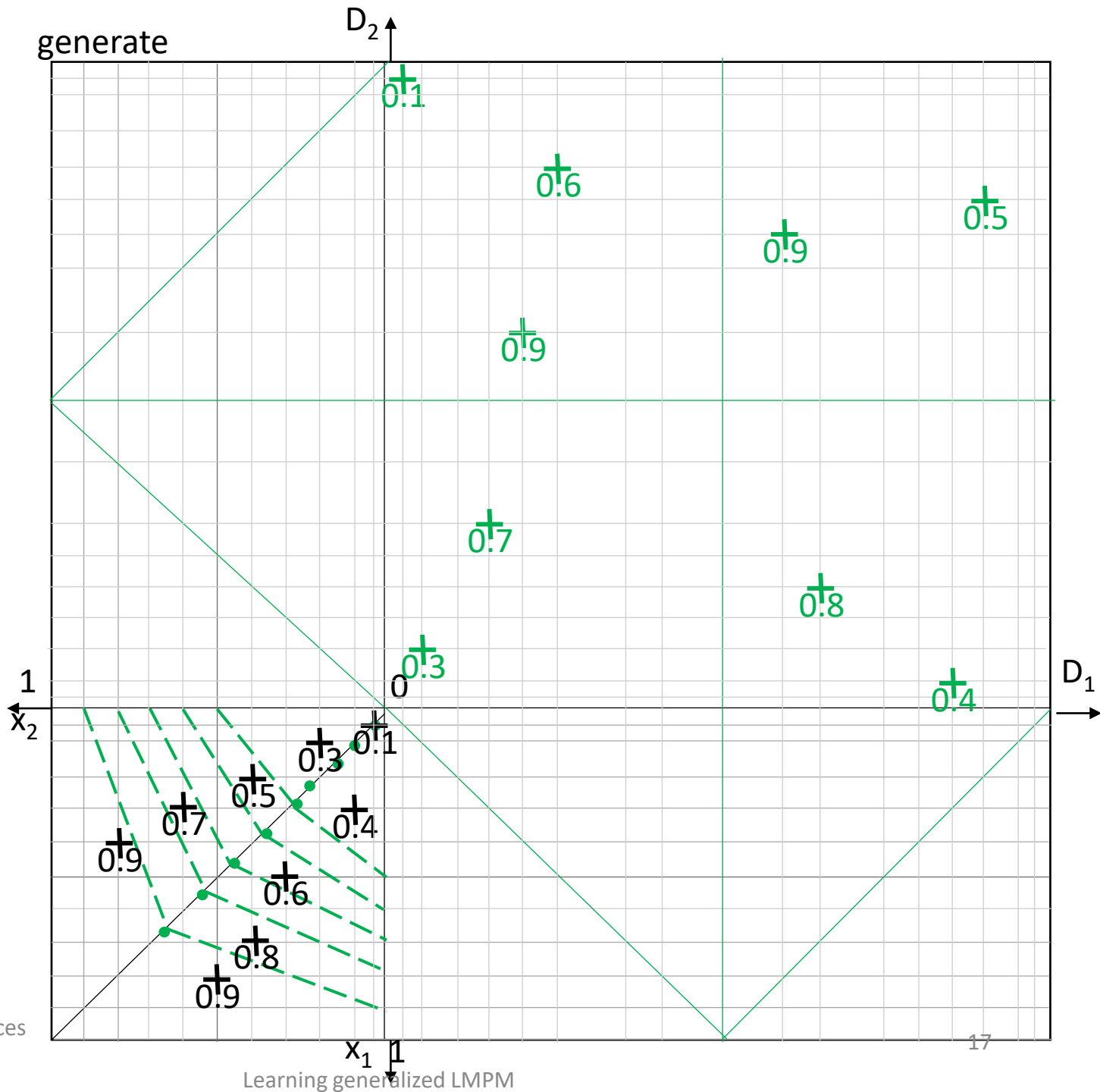
We know that attribute preferences are triangular (hill, valley) on whole domain

Let's try to learn also weighted average model, as if did not know how data were generated

+

Ex.2 data generated by product logic **disjunction** and attr. Prefs.

This is a base for generating examples
Only for copying



0.1

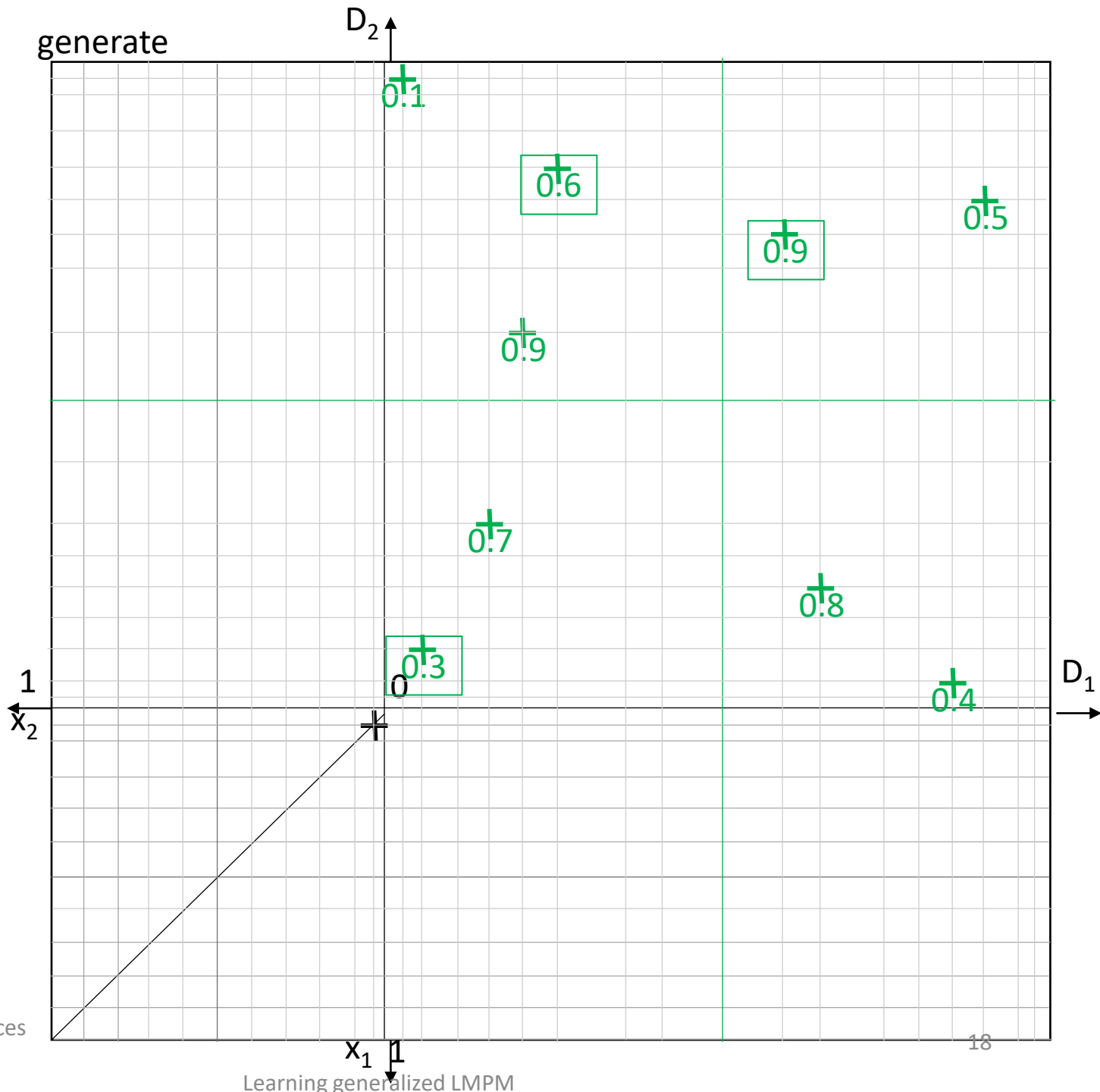
+

Ex.2 data generated by product logic disjunction and attr. Prefs.

Start to work
Decide which DC points are training and which are testing

Chose train/test

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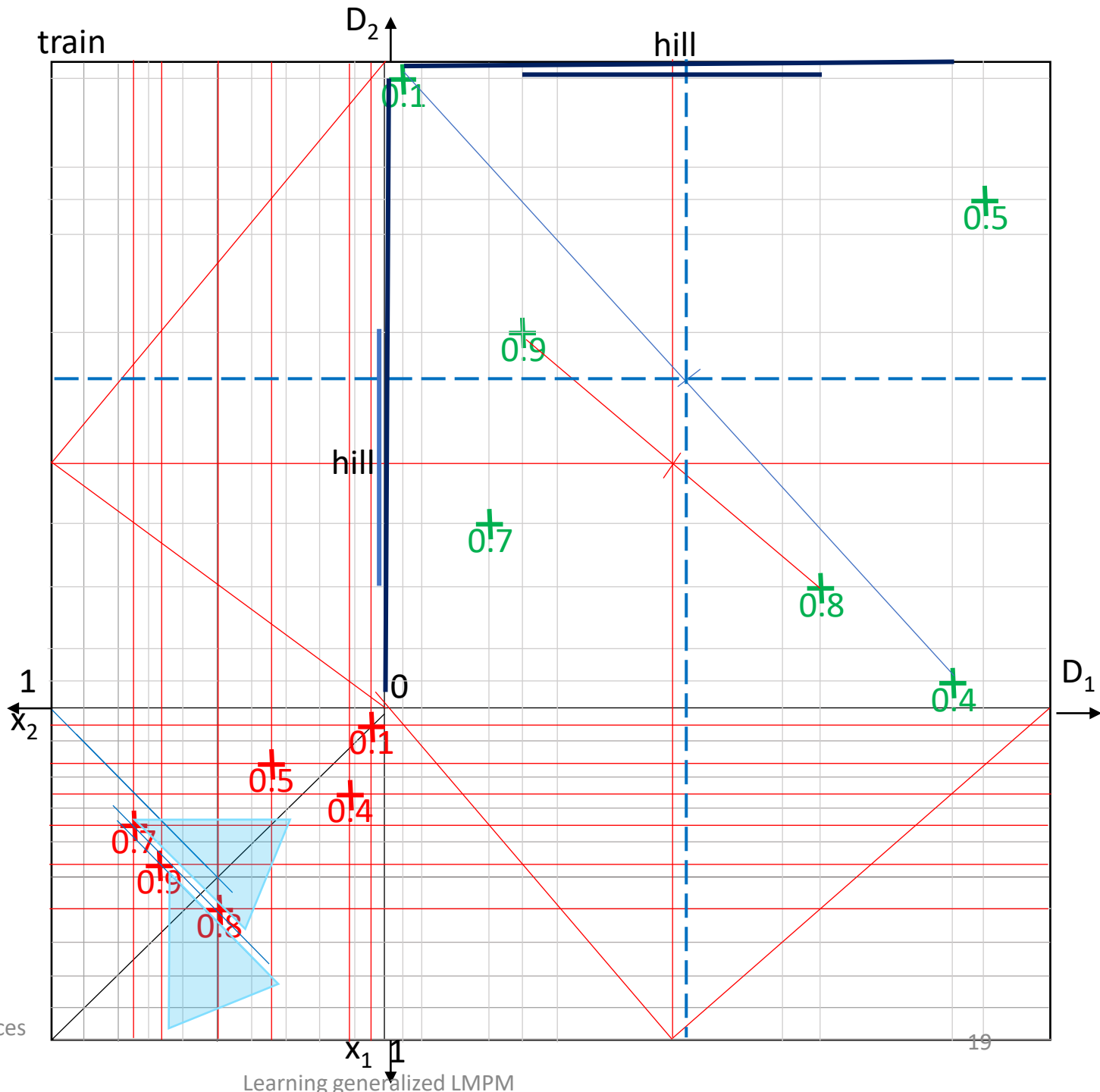
Ex.2.1 method

m2i1a1. Data generated by product logic disjunction, as in m1i1 chose first red ideal points, blue later.

Attr. prefs and training set images in PC. Again, points Pareto compliant. m2a1 by m1a1 as **weighted average (angle almost 0°)**.

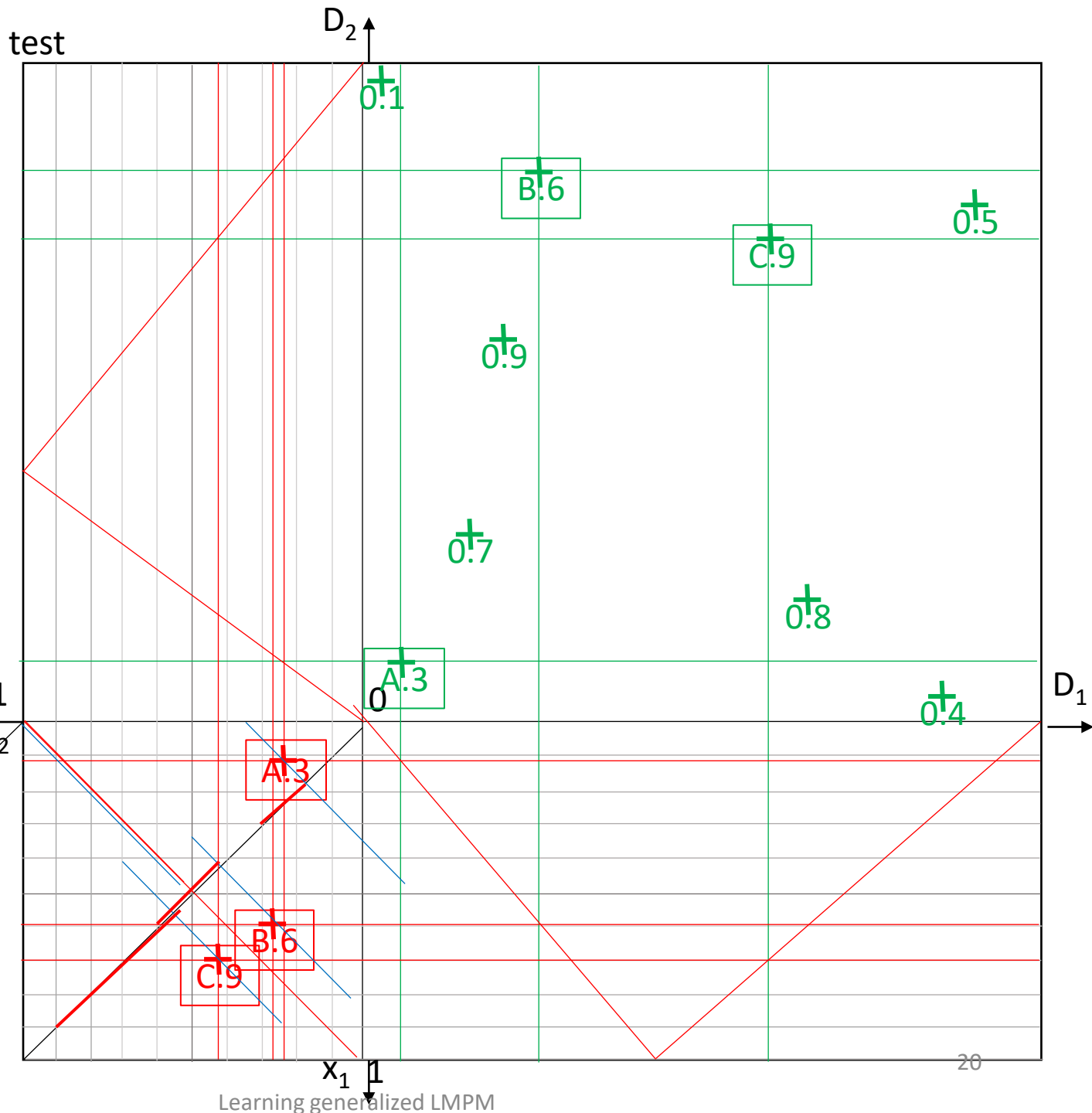
angle very small – lowers confidence substantially

0.9



+

Ex.2.1 method
i1a1. **error on test
set** (calculated to
true degree in
generating set –
here from product
disjunction) and
think of low
confidence.



1
 x_2

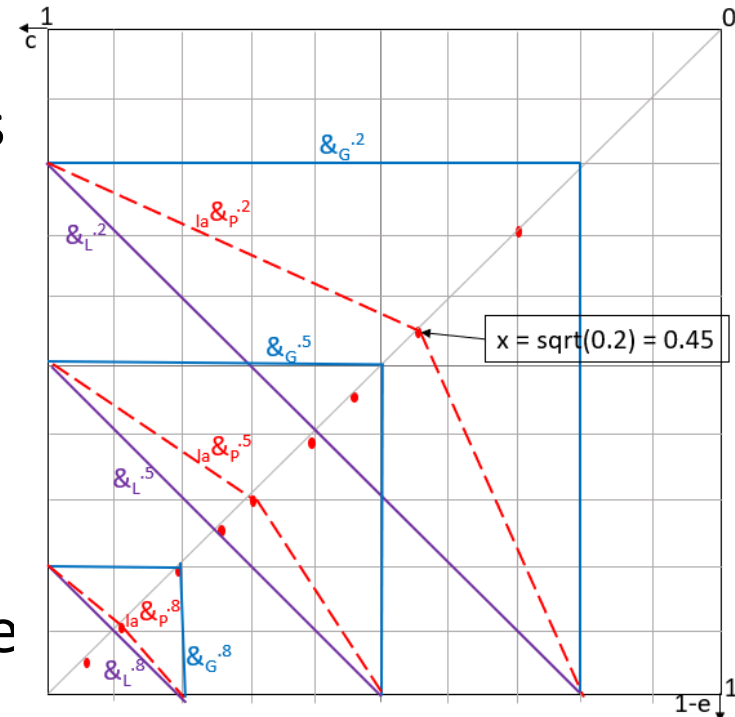
Shifted
m2i1a1

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Learning generalized LMPM

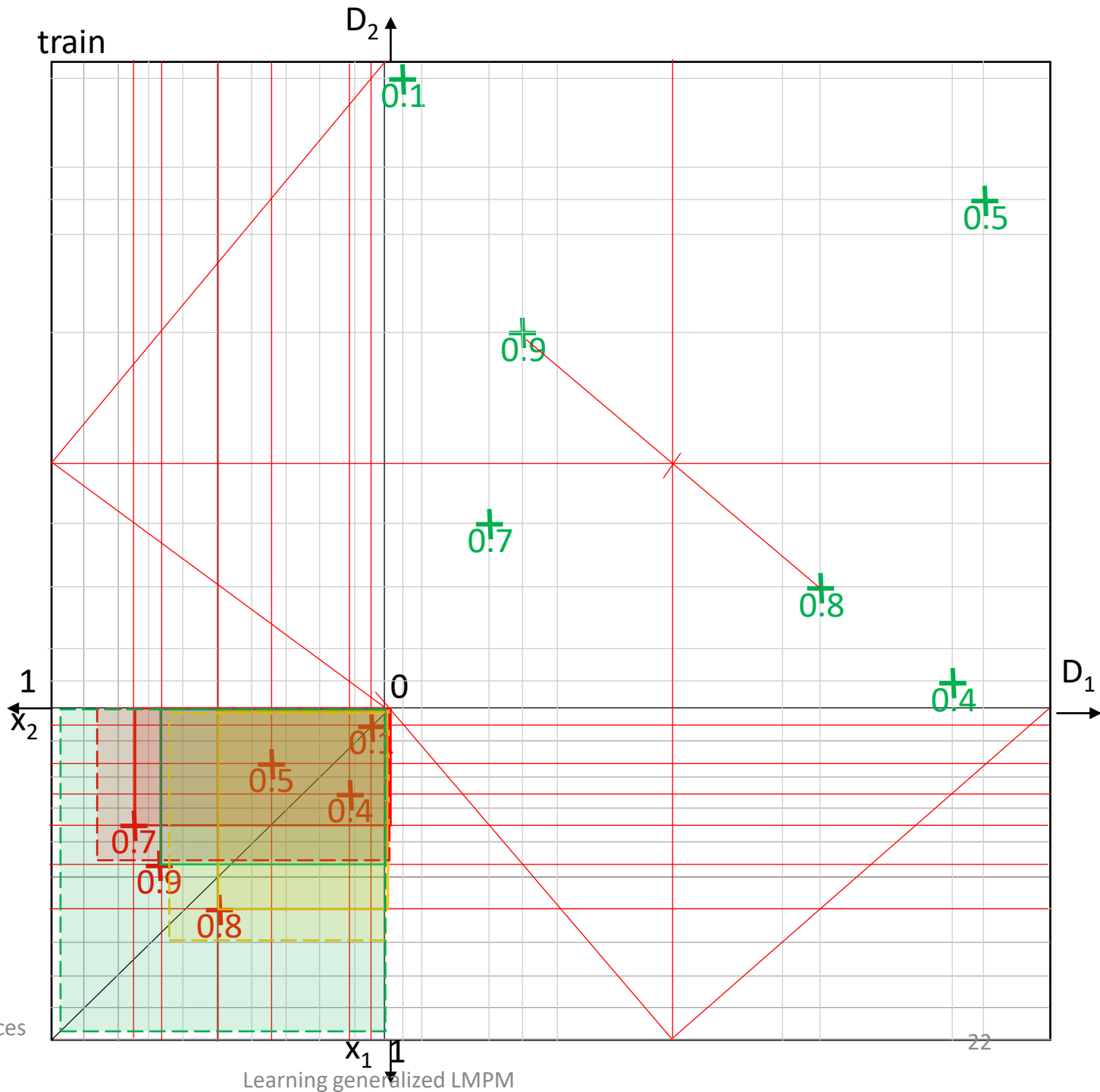
Error versus confidence

- c – confidence – proportion of compliance with model assumptions
- e - error – proportion of maximal error
- Ideal $c=1, e=0$ (depict $c, 1-e$)
- How to aggregate c and $1-e$ to usability of learning results?
- Guess: c - e -aggregation is conjunctive
 - Minimal confidence $c=0$ and error $e=1$ make results of learning not usable. So, on 0-axis we have usability 0
 - Are $c, 1-e$ independent? Product logic conjunction?
 - Do $c \uparrow 1, 1-e \downarrow 0$ behave opposite, i.e., $c \uparrow 1, e \uparrow 1$, rather not Lukasiewicz
 - Dependent? Goedel logic? Probably yes.
 - **How to test these hypotheses?**



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Ex.2.2 **method 2a**
and 2b Data, attr.
Prefs, training set
in PC as before.
Let's try to find agg.
In form of Eckhardt
geometry / Pareto
min (solid outline)
/max (outline
dashed) method.
There are no
violations of Pareto
order, so
confidence is high.



0.9

+

Ex.2.2 method 2a – Pareto minimal region.

error on test set

Image of test set in PC is always same (point identifiers are pref.score)

0.3 lies in Eckhardt geometry minimal region of 0.5

(learned from training example) – gives to error 0.2

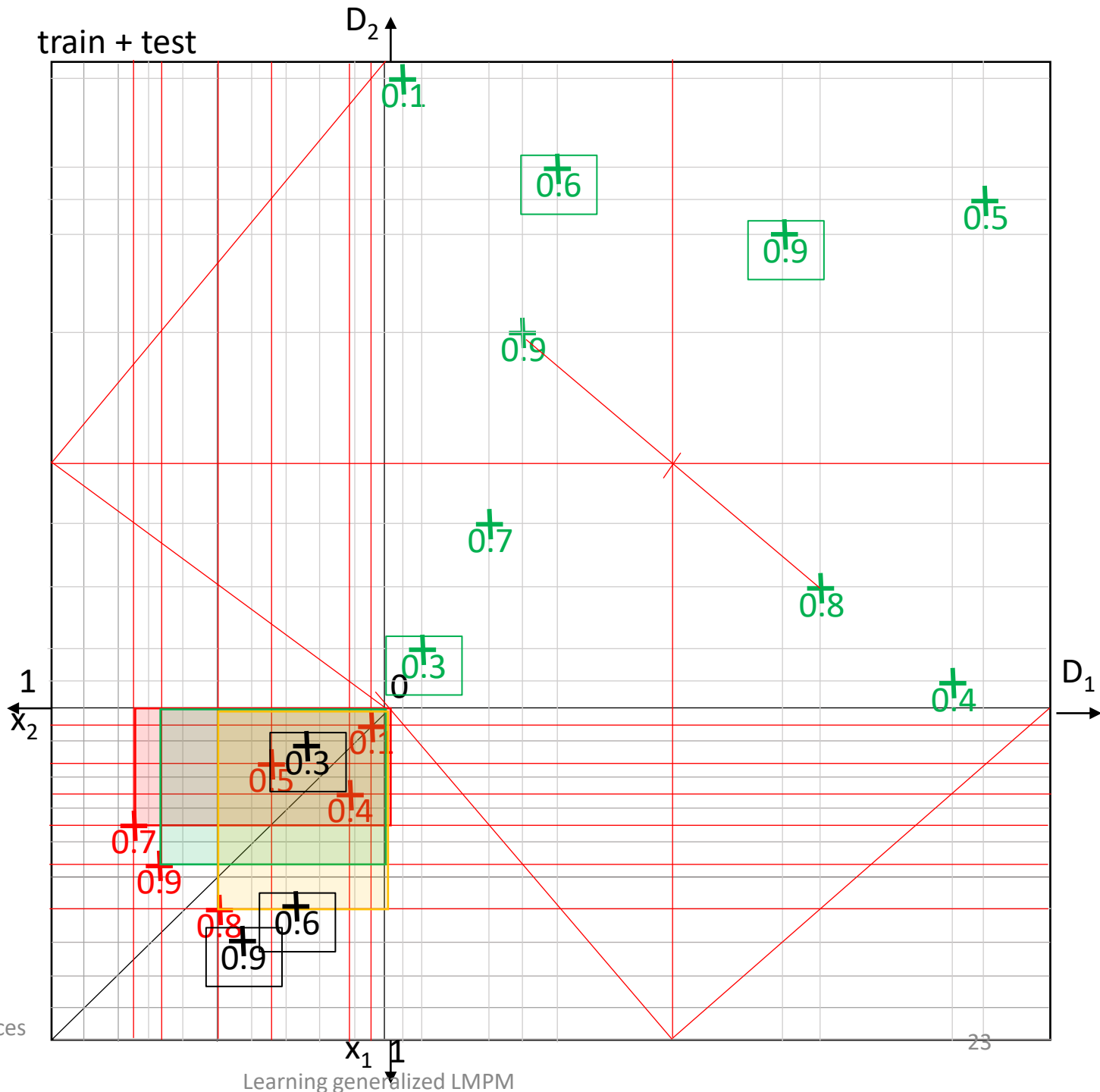
0.6 lies in 0.8 e=0.2

0.9 lies in 1, e=0.1

In total error = 0.5

0.9

train + test



+

Ex.2.2 method 2b – Pareto maximal region.

error on test set

Image of test set in PC

is always same

Image of test set in PC

is always same

(point identifiers are pref.score)

0.3 lies in Eckhardt

geometry maximal

region of 0.4 –

gives to error 0.1

0.6 lies in 0.4, $e+0.1$

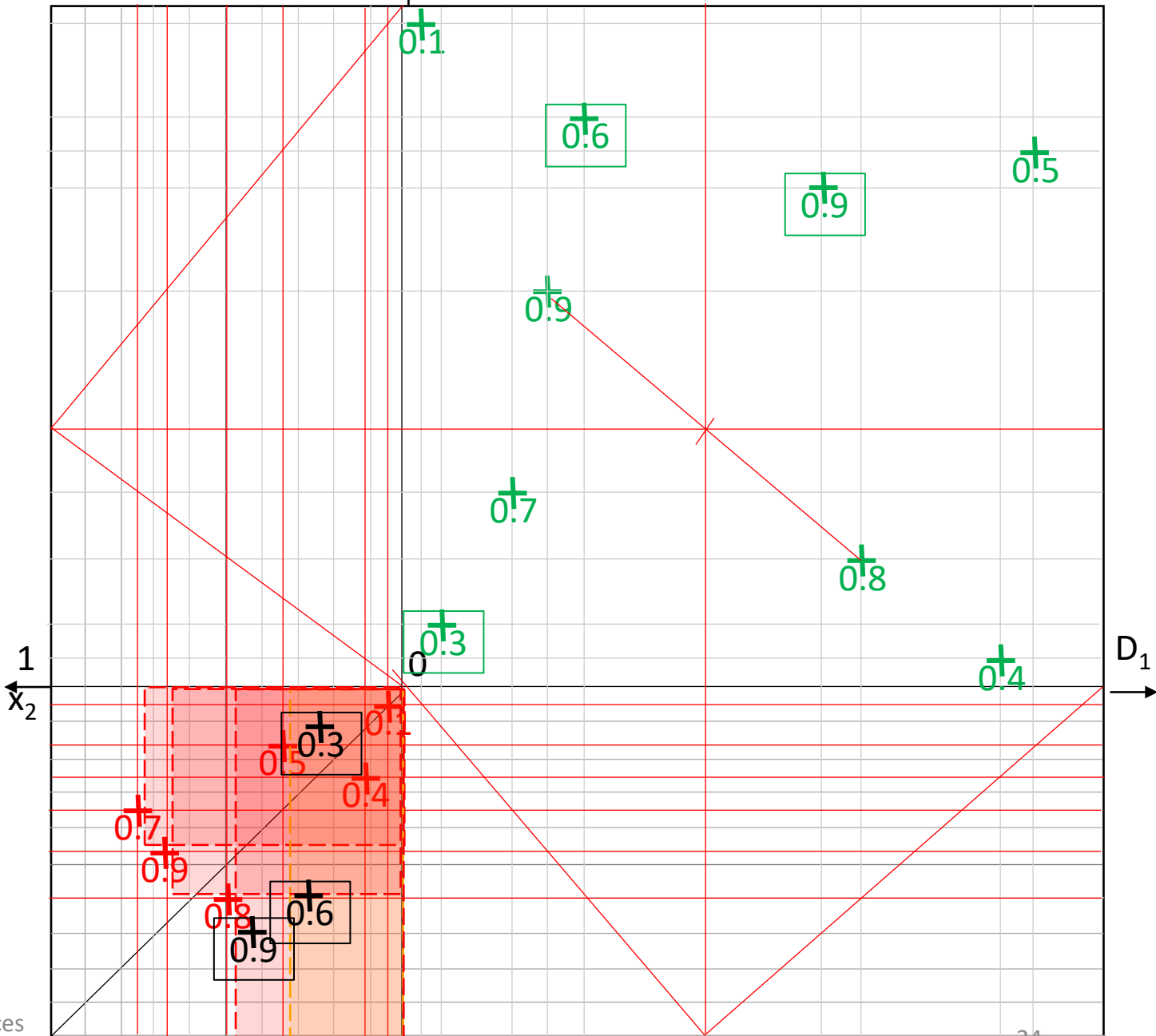
0.9 lies in 0.5, $e+0.4$

Total error = 0.6

+

train + test

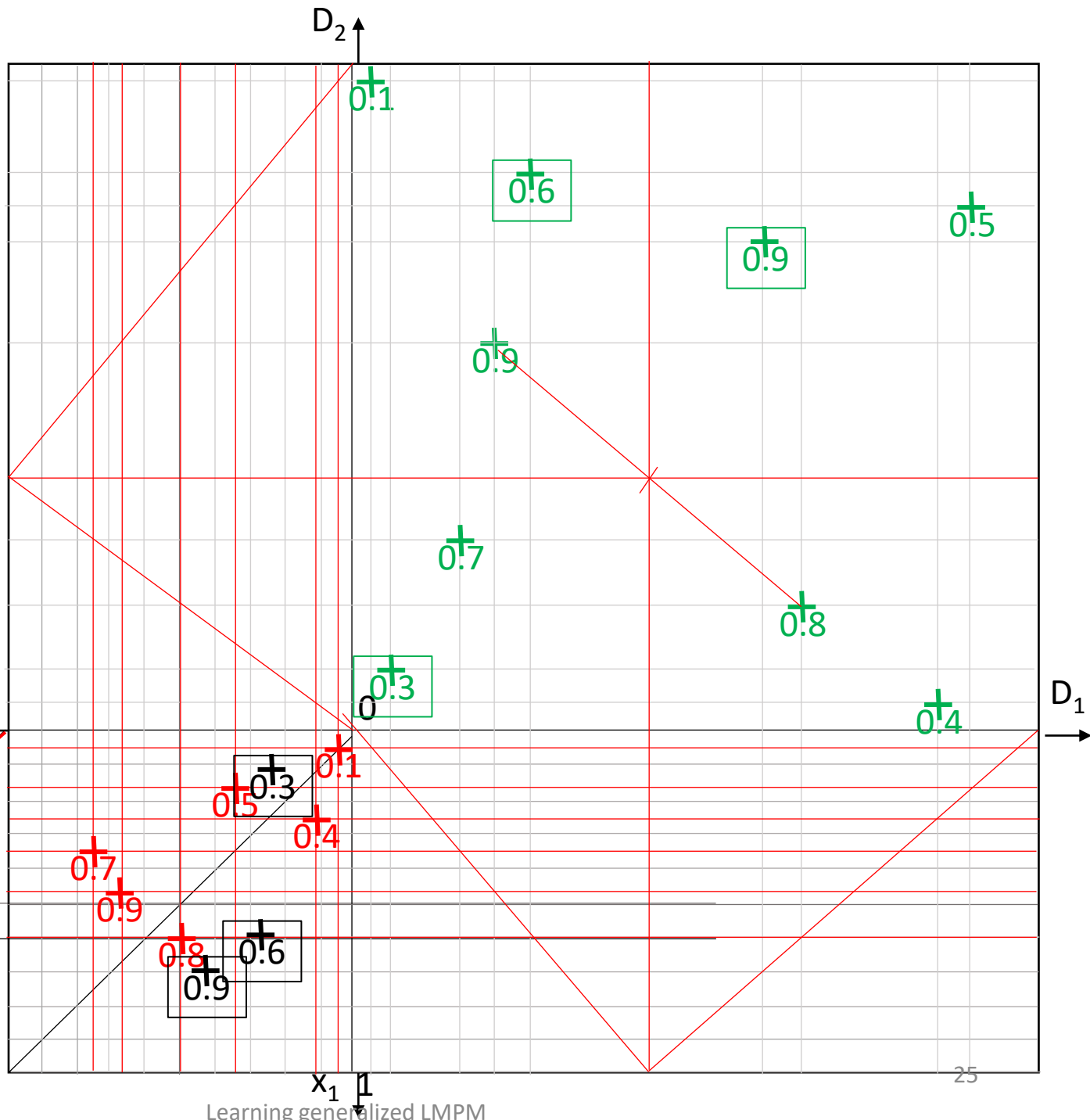
D_2



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Ex.2.2 comparing methods 1, 2a, 2b
error on test set
 Image of test set in PC is always same
 Image of test set in PC is always same
 (point identifiers are pref.score)

a1 – error graphical
a2a – error = 0.5
geometry minimal
 a2b – error = 0.6



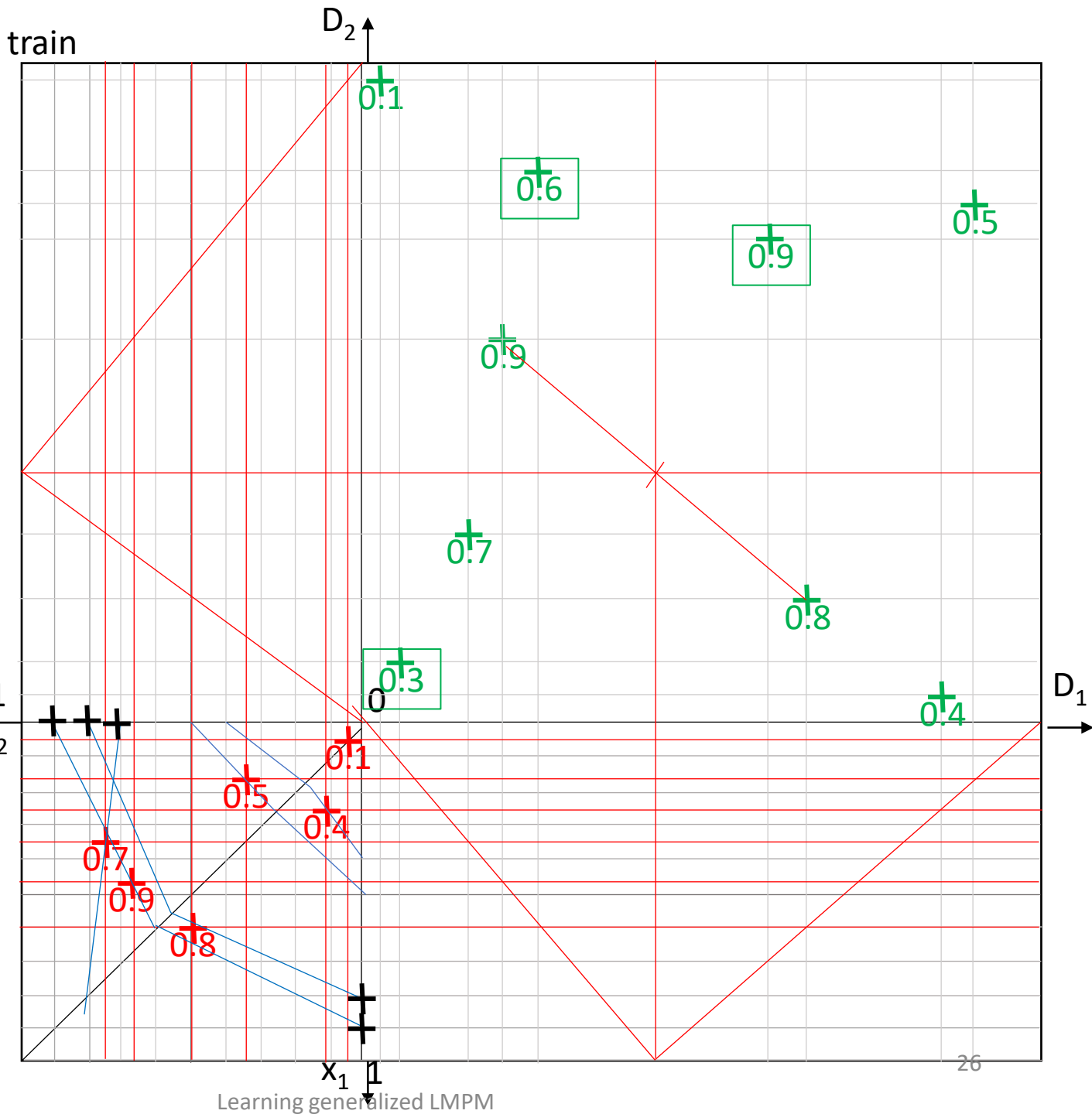
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Ex.2.3 method 3.

Data, attr. Prefs, training set in PC as before.

Let's try to find agg. in form of many valued disjunction – connecting points to known behavior on axis and corresponding intersection with diagonal. Confidence is 5/6 high – there is only one violation with 0.7 contour line. For test set we must approximate corresponding contour lines

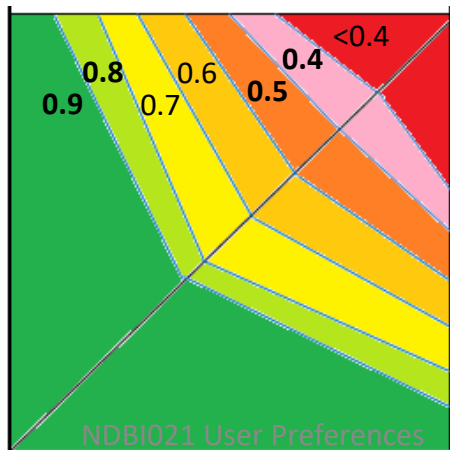
0.9



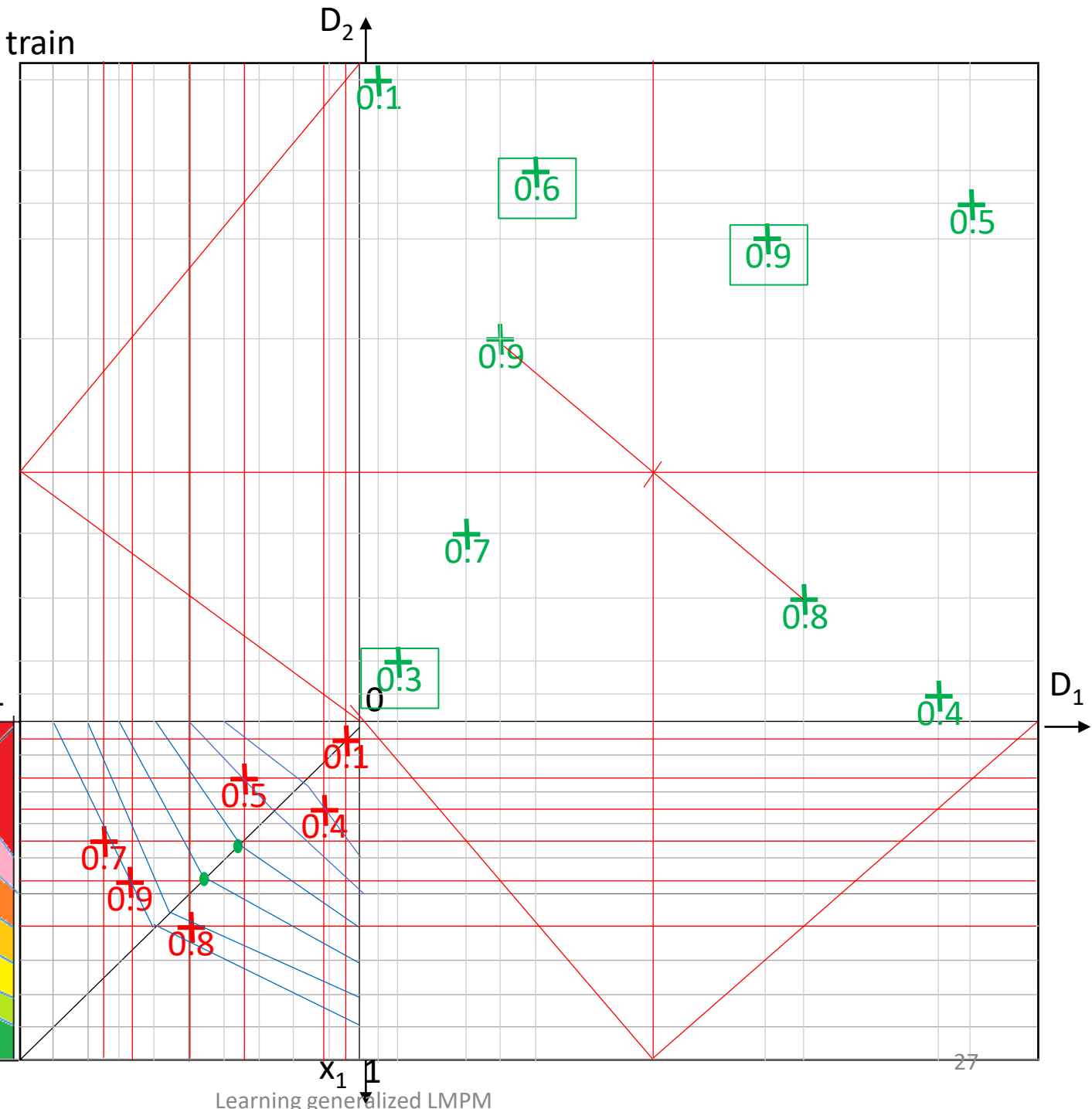
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Ex.2.3 method 3. Approximating missing contour lines

Data, attr. Prefs,
training set in PC as
before. We found
agg. in form of many
valued disjunction.
Missing 0.6 and 0.7
are heuristically
constructed by
equidistant points on
diagonal.



train



+

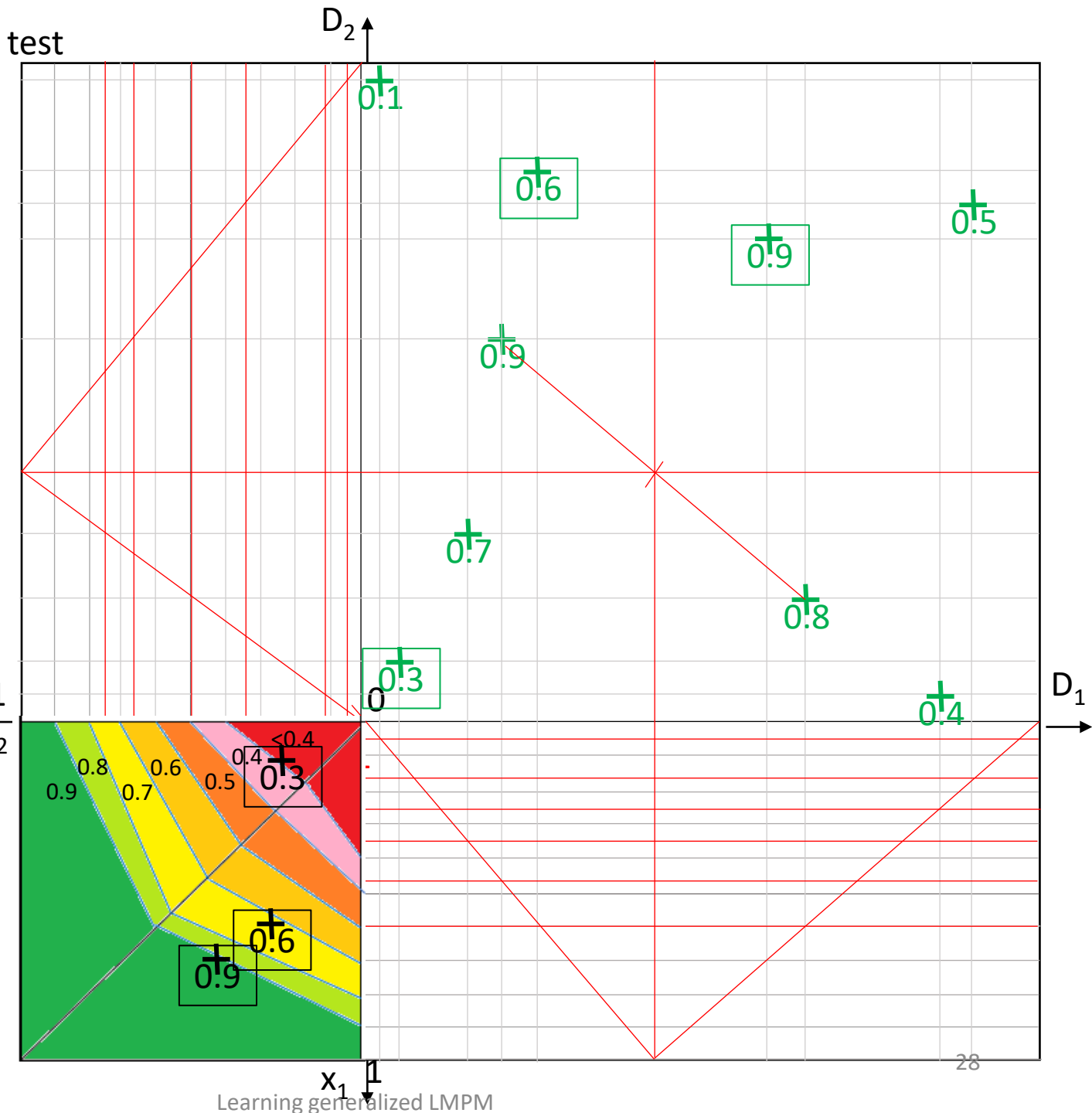
Ex.2.3 method 3.

Error on test set

Data, attr. Prefs, training set in PC as before. We found agg. in form of many valued disjunction. Missing 0.6 and 0.7 are added. As f_1, f_2 are added, images in PC are same.

0.3 lies in region of 0.4 – gives error +0.1
0.6 gives to error +.1
0.9 lies on border of 0.9, so error is 0

Overall error is 0.2



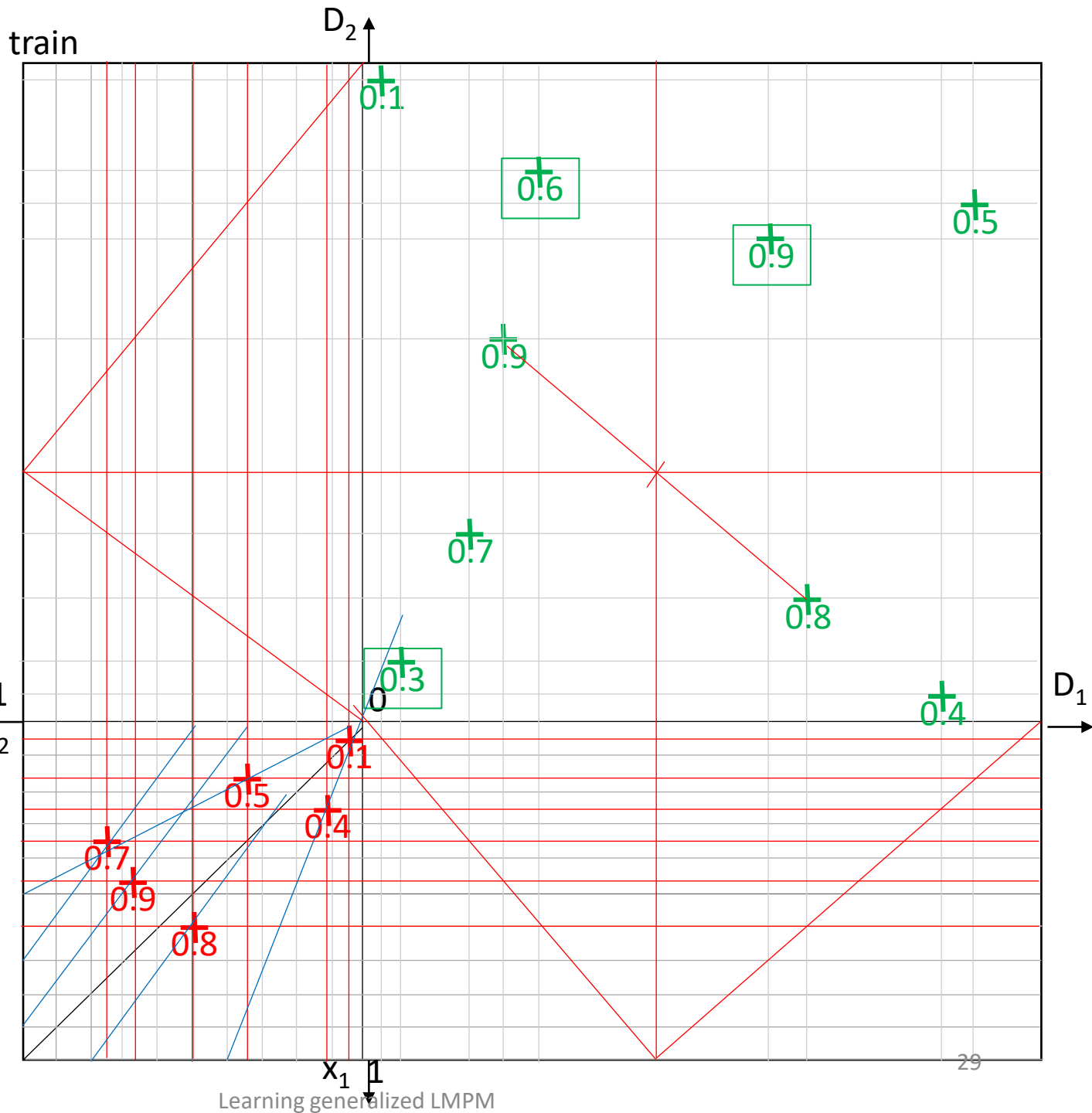
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Ex.2.4 **method 4**.
Data, attr. Prefs,
training set in PC as
before.

Let's try to **find
agg. in form of
many valued
conjunction** –
connecting points
to known behavior
on axis and
corresponding
intersection with
diagonal.

Confidence is very
low, zero – there is
no intersection of
estimated contour
lines with diagonal
– **learning failed**

0.9



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Example2 résumé

attr. pref. easy as
we know triangles
over whole domain

We do not know @
models and have to
try many

Methods

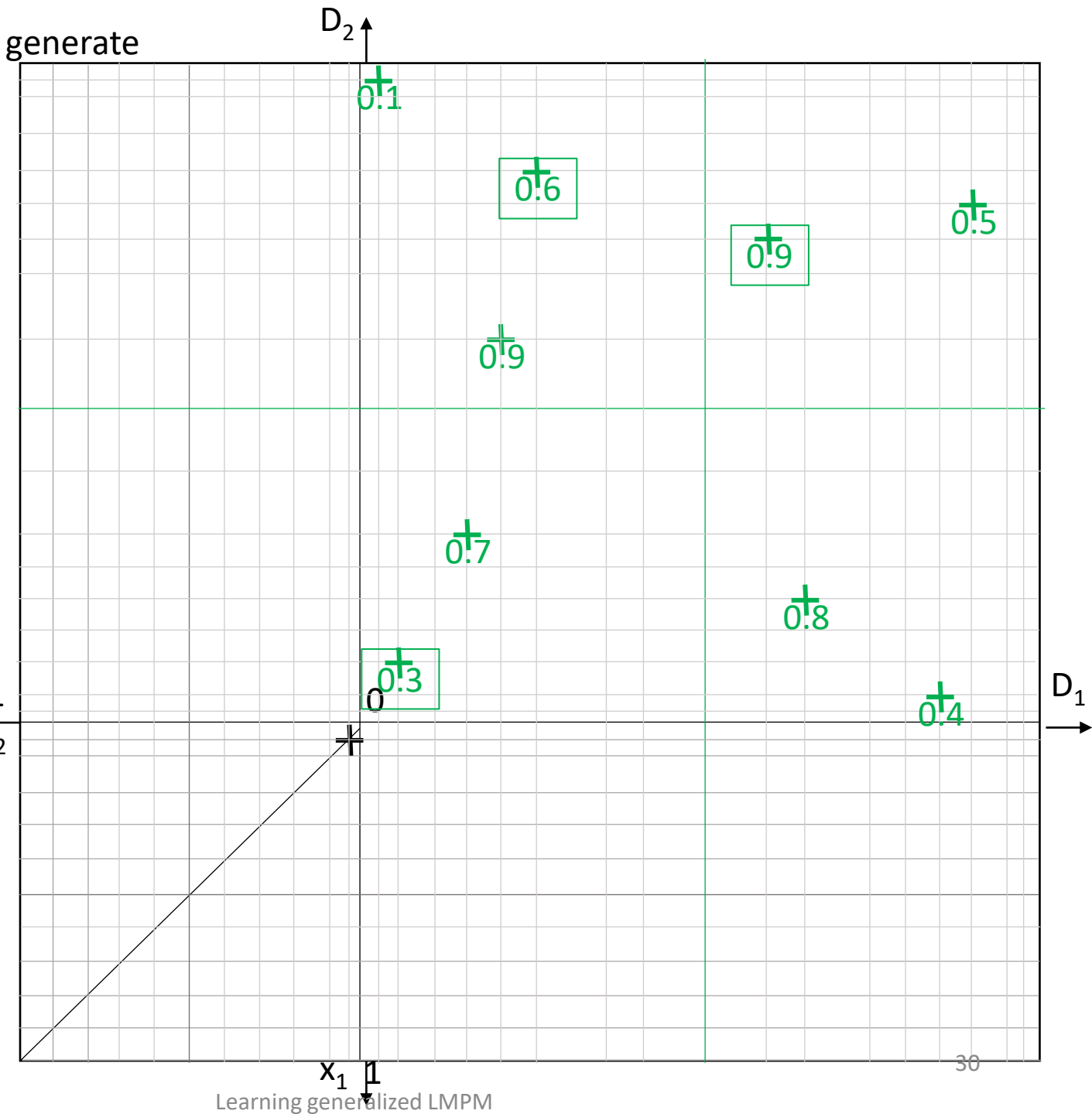
a1 – $e > 0.6$

a2a – $e = 0.5$

a2b – $e = 0.6$

a3 – $e = 0.2$

a4 – failed $c = 0$



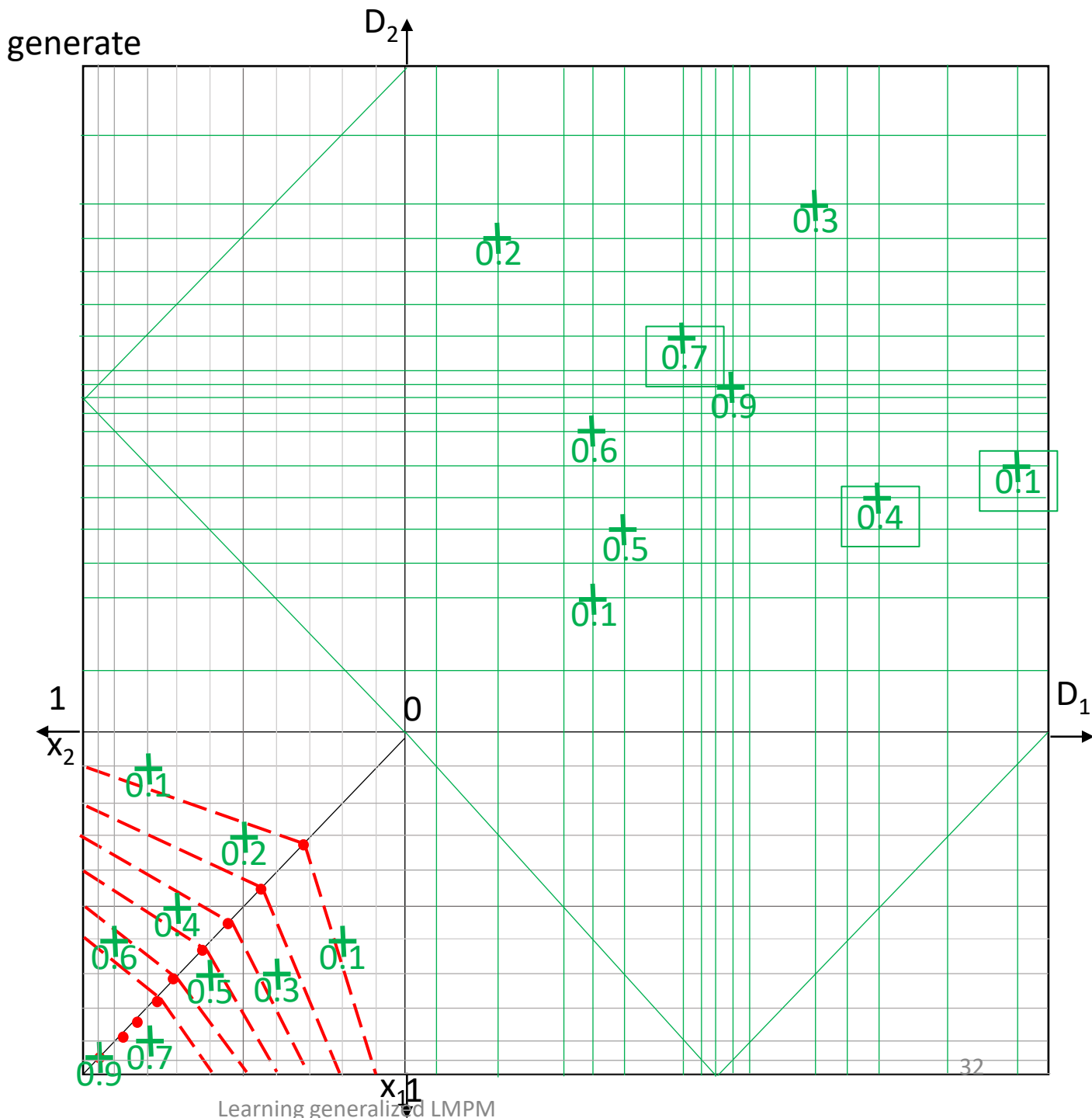
Experiment 3.

Data generated by product **conjunction** on respective
PC contour lines

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Ex.3 generated by product logic
Conjunction, again
Nine different preference degrees.

Basis for generating data points
Only for copying



0.9

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Learning generalized LMPM

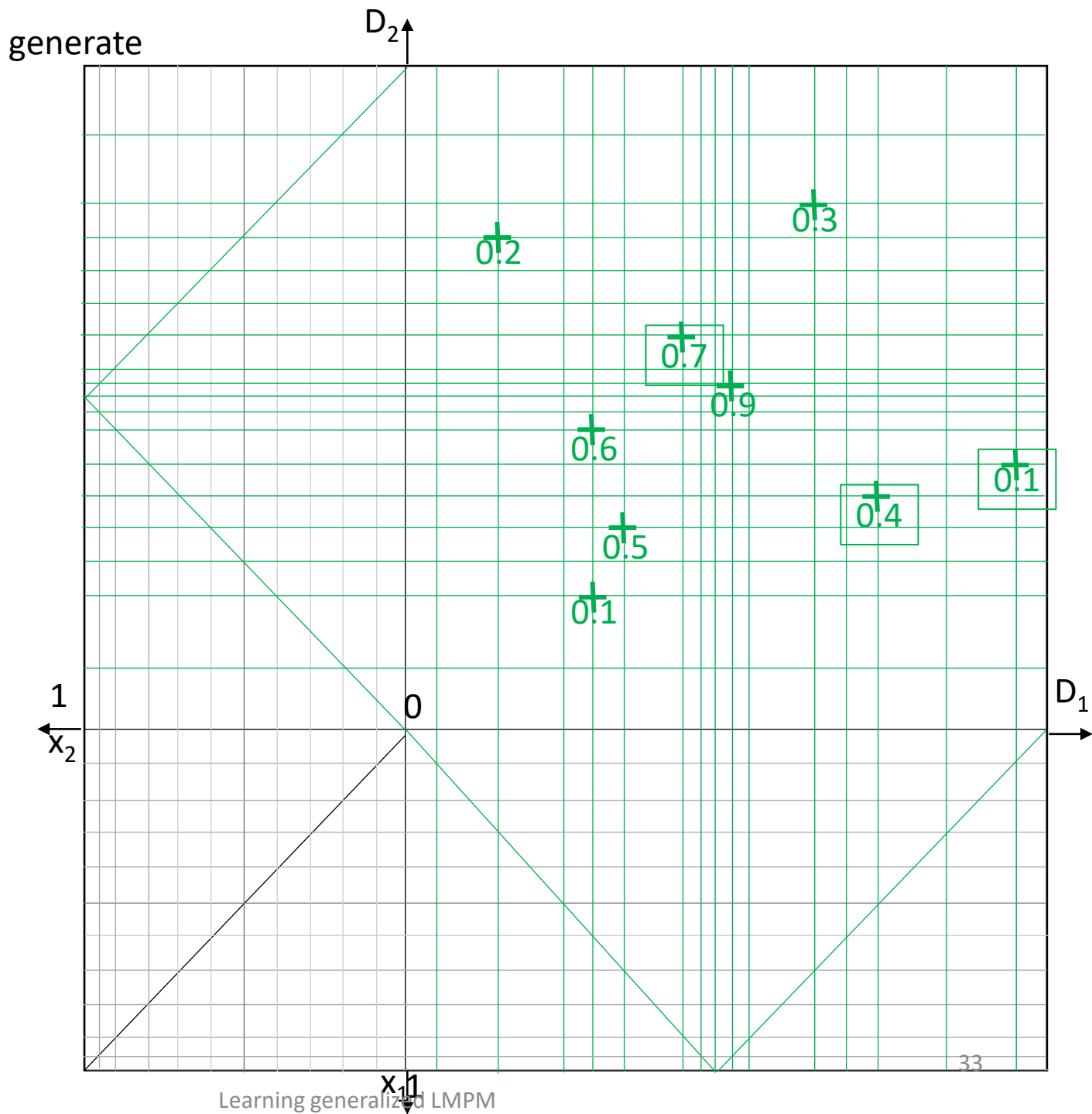
+

Ex.3 generated by product logic Conjunction, again Nine different preference degrees.

Basis for generating data points
Only for copying

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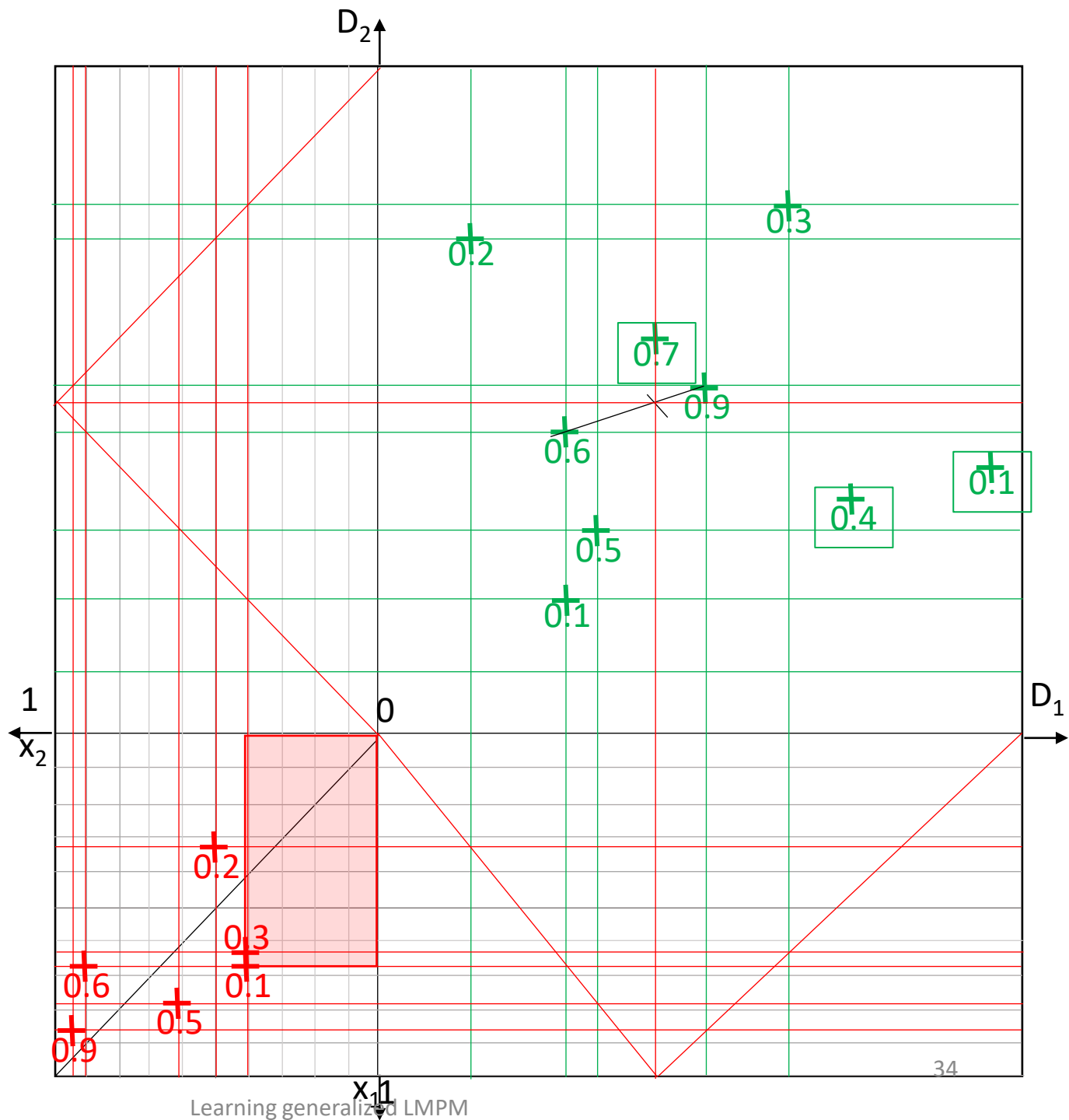
Ex.3 data generated by product logic conjunction

i1 as before

One Pareto violation 0.3 is dominated by 0.1

Does it influence confidence?

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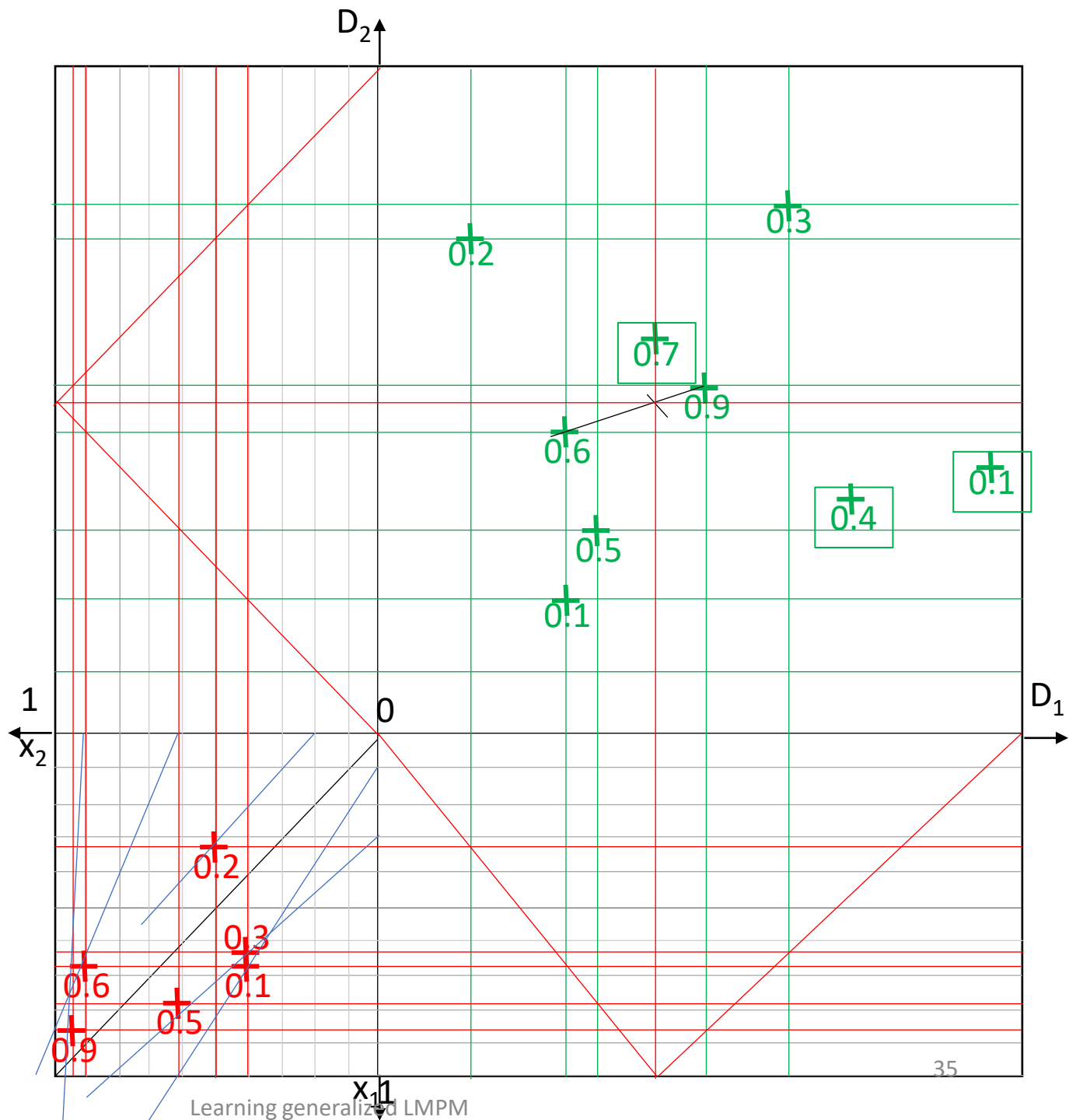


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Ex.3 data generated by product logic conjunction

a1 - Or-like approx. never intersects diagonal

m3i1a1 Confidence = 0



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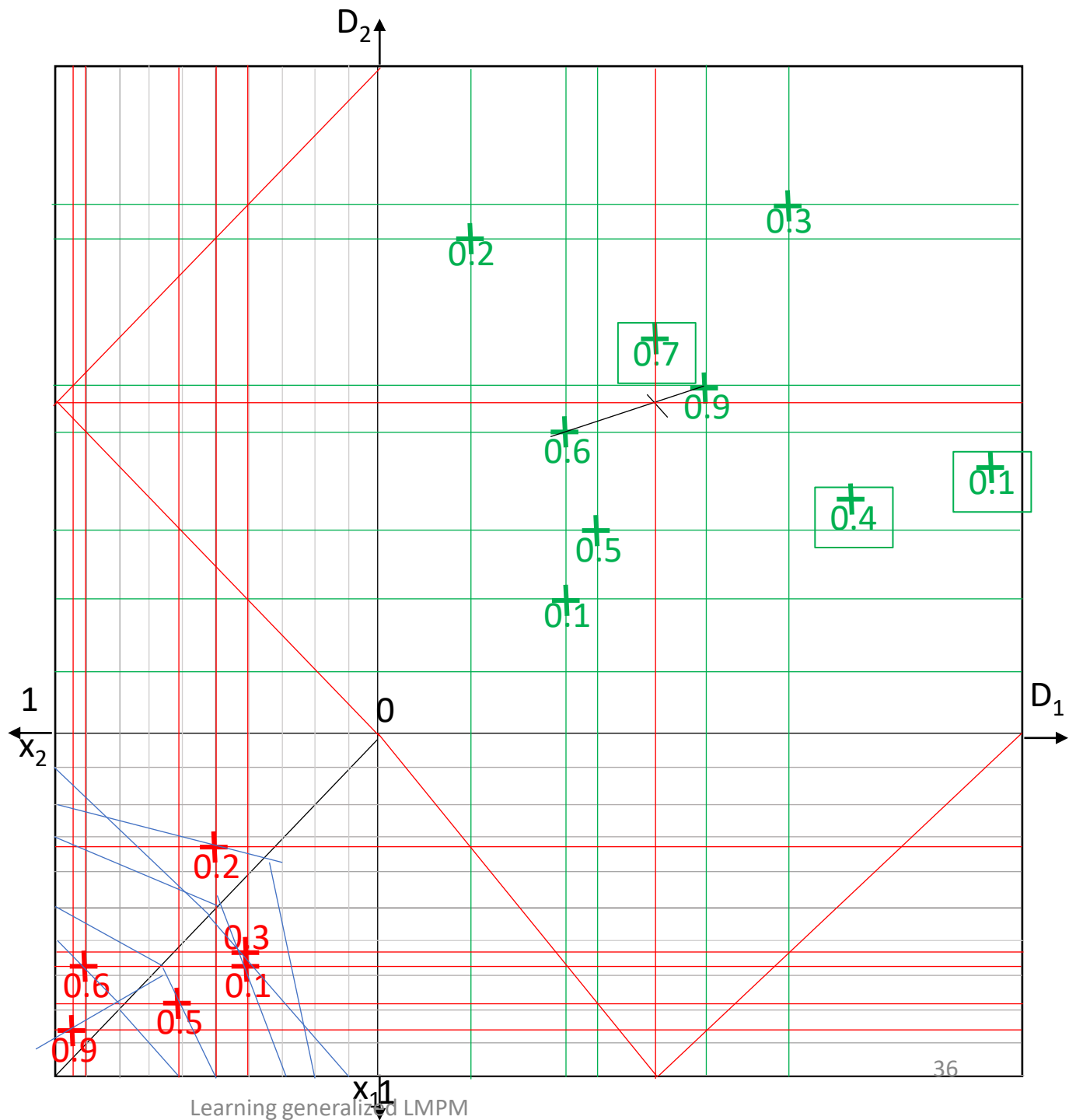
Ex.3 data generated by product logic conjunction

a2-And-like aprox. intersects diagonal

0.1 causes problem, decreases confidence

Also 0.9 violates contour lines 0.6 and 0.5

Let us continue with 0.2, 0.3, 0.5, 0.6 which are order compliant and do not intersect smaller / larger lines

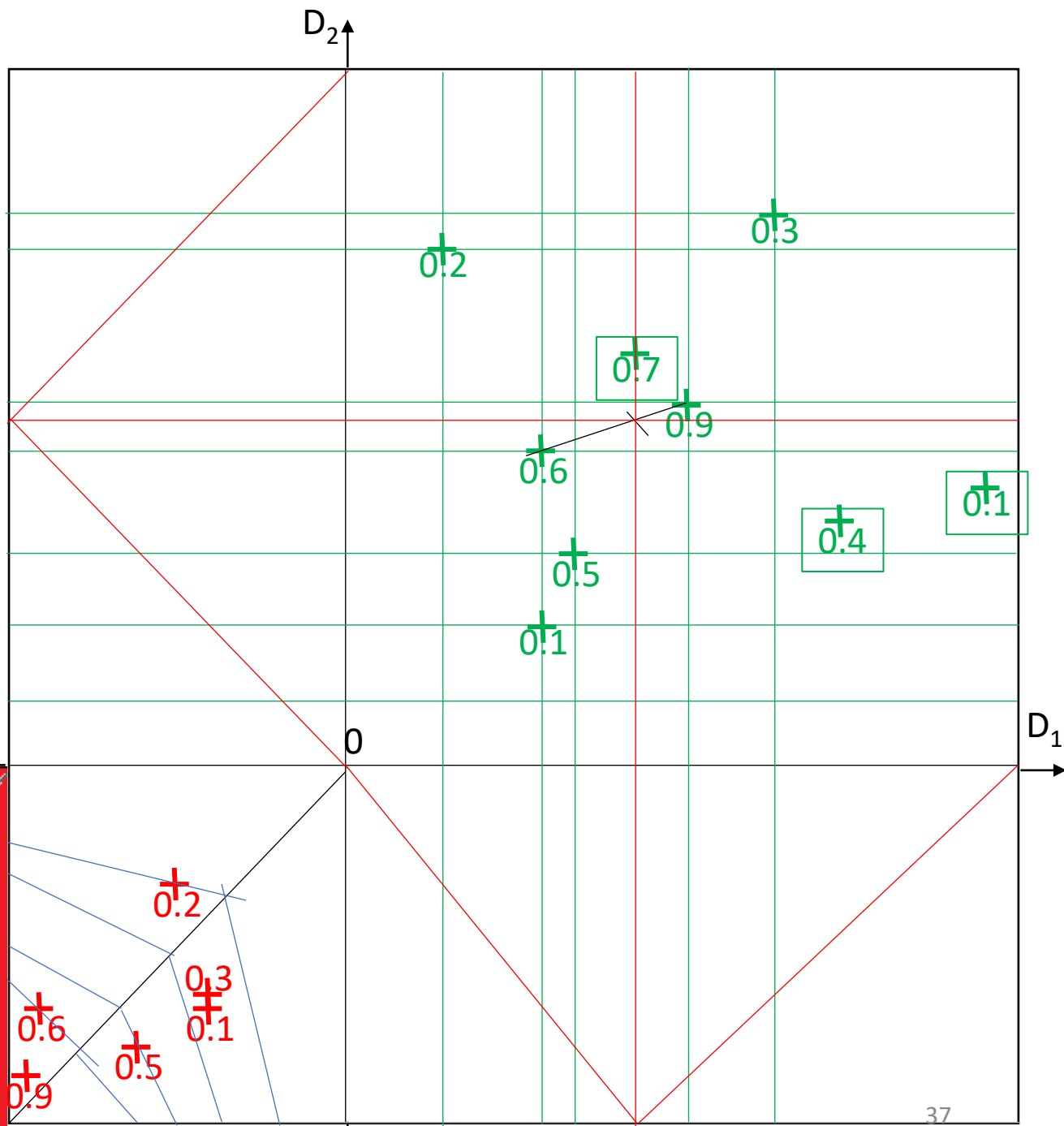


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Ex.3data
a2-And-like aprox.
intersects diagonal

0.1 problem,
0.9 violates

continue with 0.2,
0.3, 0.5, 0.6

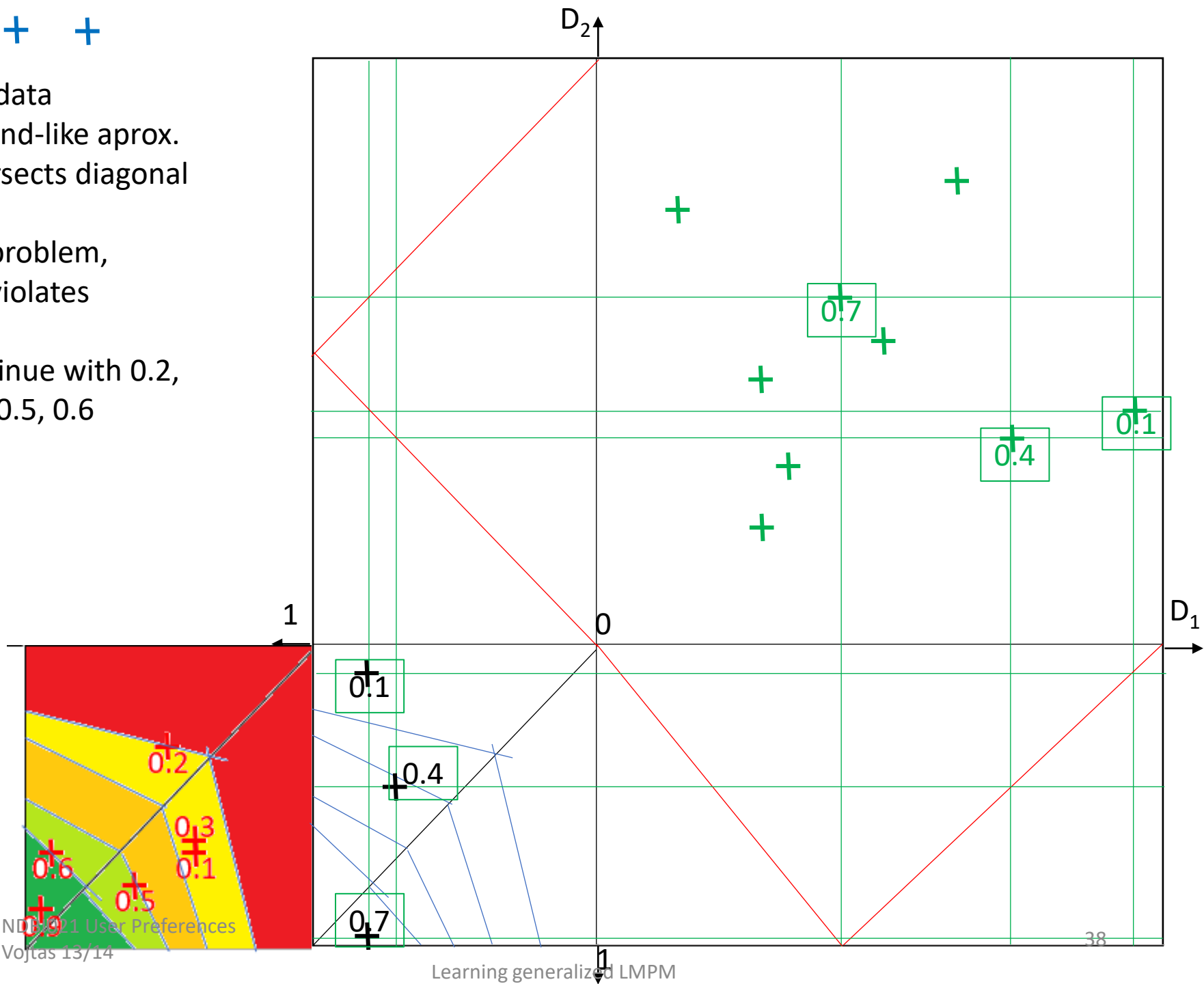


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Ex.3data
a2-And-like aprox.
intersects diagonal

0.1 problem,
0.9 violates

continue with 0.2,
0.3, 0.5, 0.6



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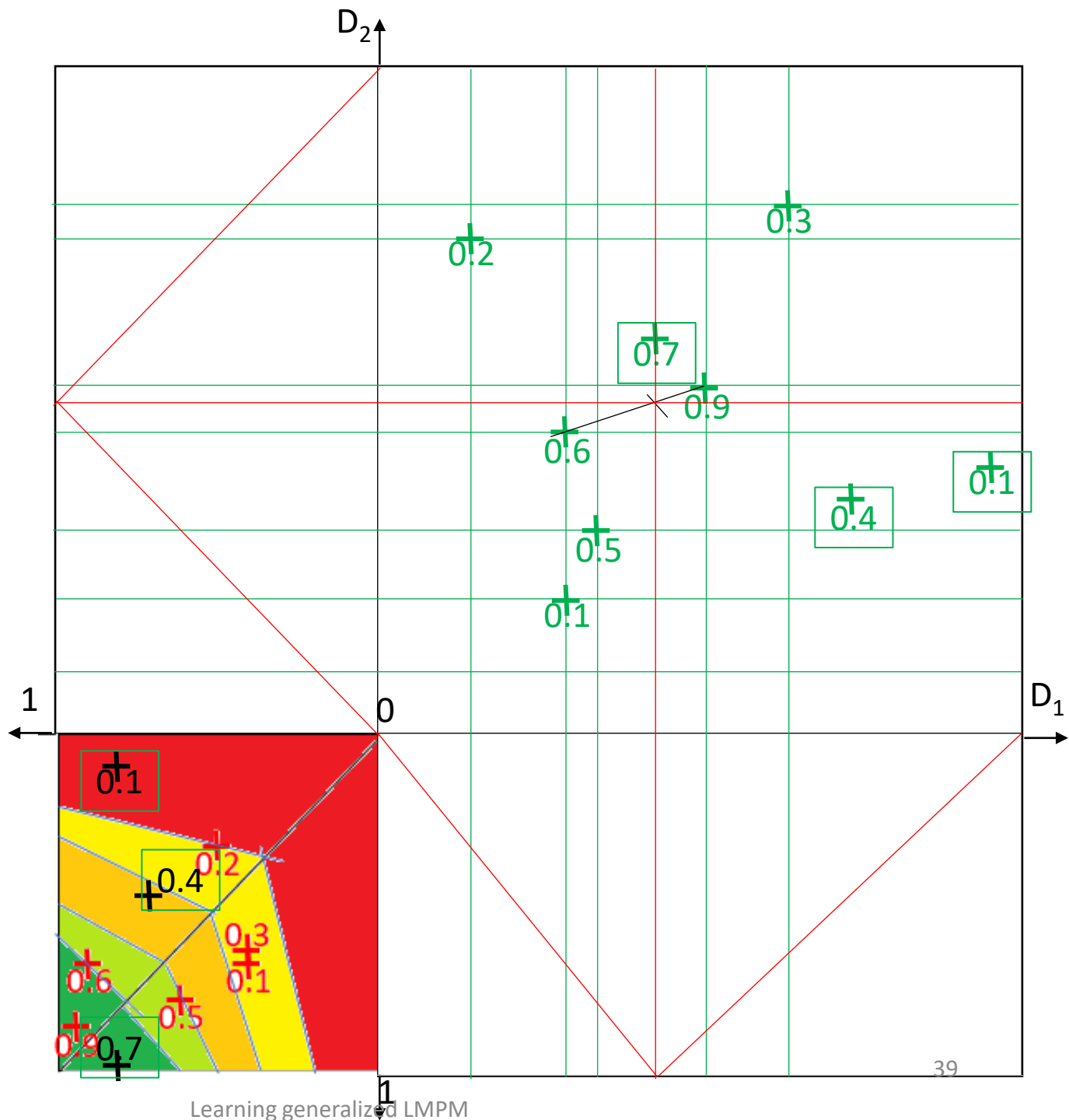
Ex.3 data generated by product logic conjunction

a2-And-like aprox. intersects diagonal

0.1 causes problem, decreases confidence

Also 0.9 violates contour lines 0.6 and 0.5

Let us continue with 0.2, 0.3, 0.5, 0.6 which are order compliant and do not intersect smaller / larger lines



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Example 3 résumé

3 data generated by
product logic
conjunction

i1 makes candidate data
in PC with one violation
of Pareto order

We do not know @
models and try
conjunction and
disjunction

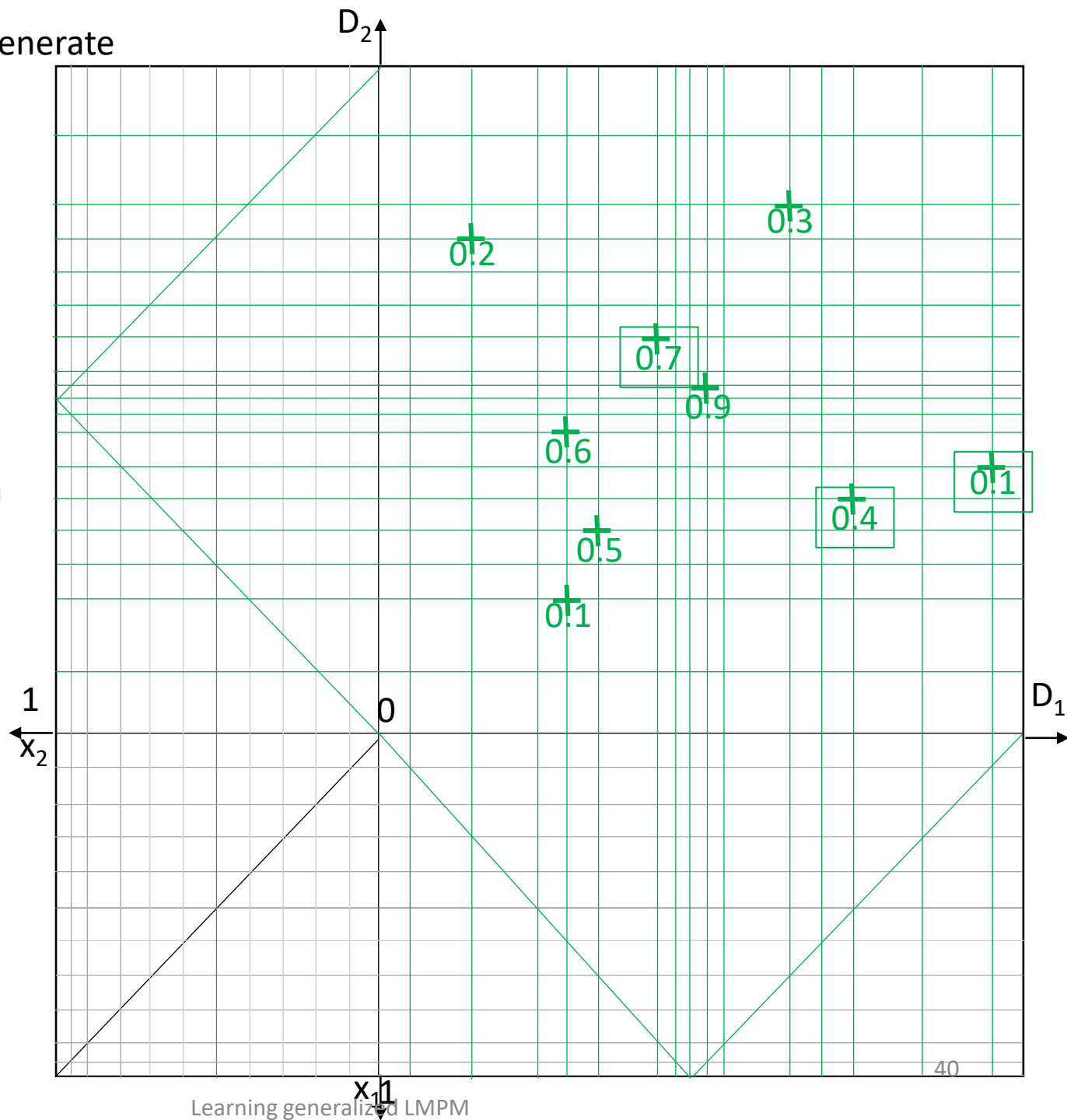
Methods

a1 – or like fails

a2 – fit well

Rather low confidence

generate

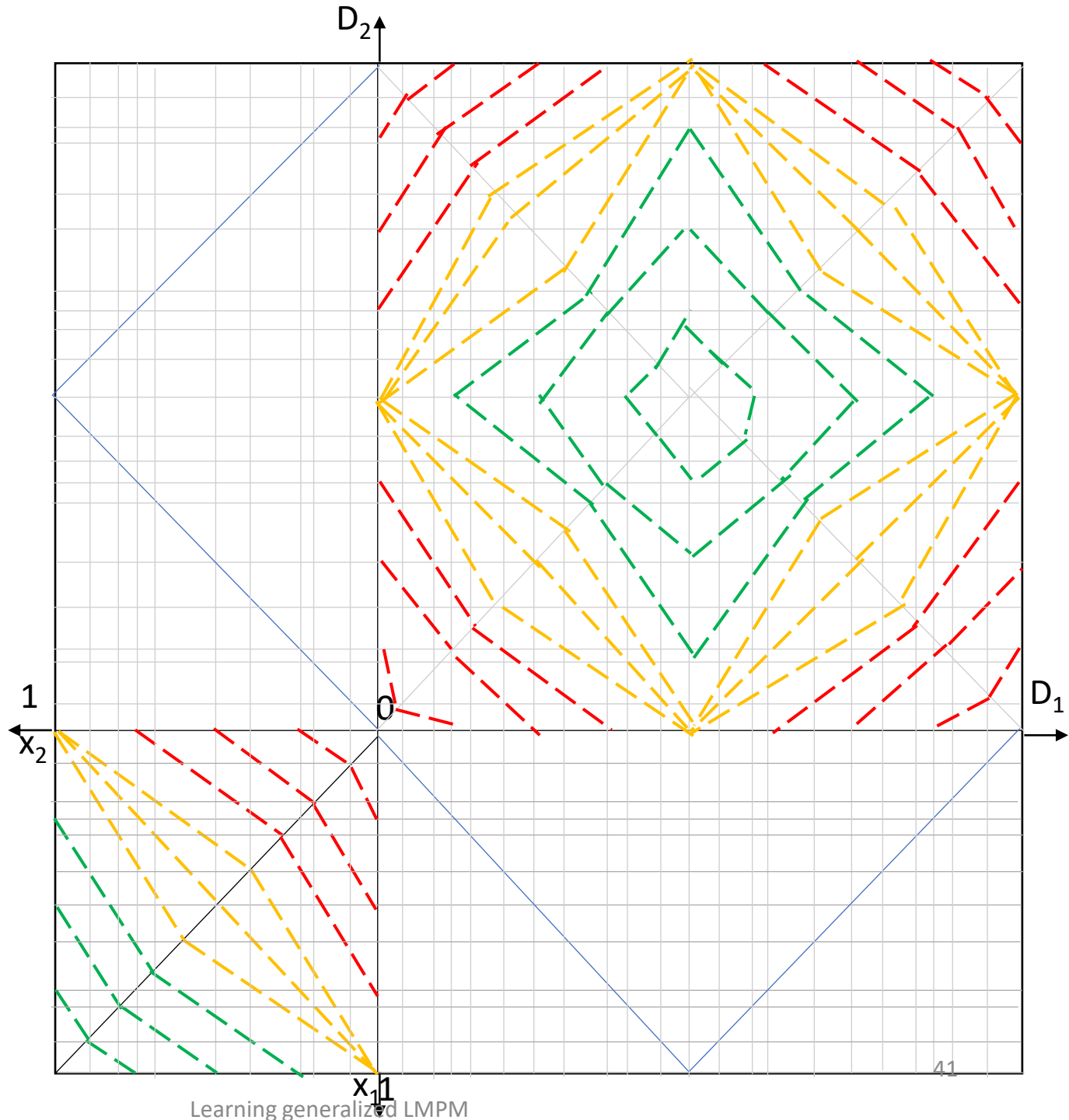


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Ex.3 generate regular contour lines in the PC,

Fix attribute preferences, construct corresponding images in DC and chose points in layers between contour lines in the DC

Now arbitrary choice in DC layers gives a learning task



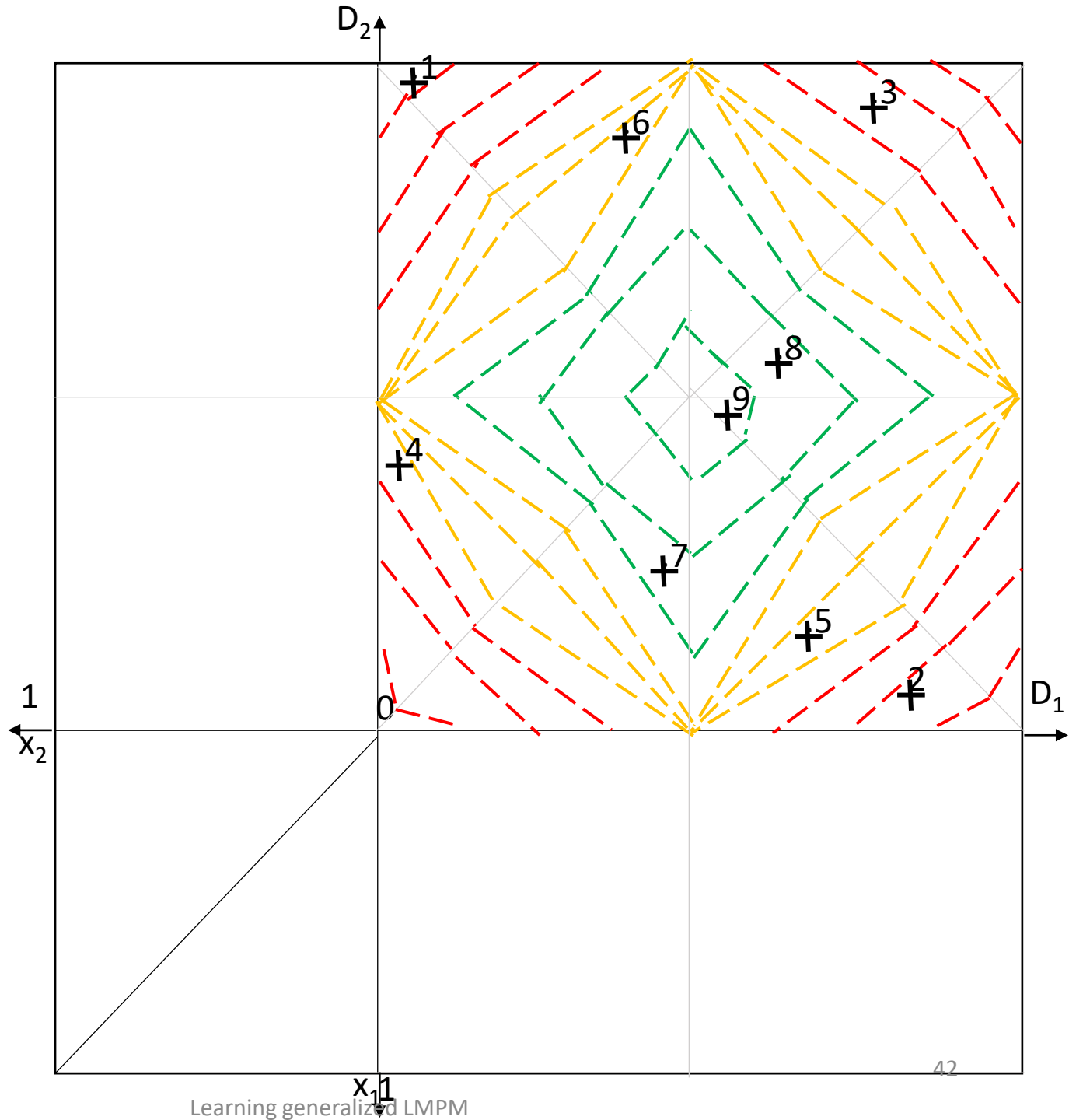
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Ex.3 **generate** regular contour lines in the PC,

Fix attribute preferences, construct corresponding images in DC and chose points in layers between contour lines in the DC

Now arbitrary choice of points in DC layers gives a learning task

We can try to cheat some methods



+1

+

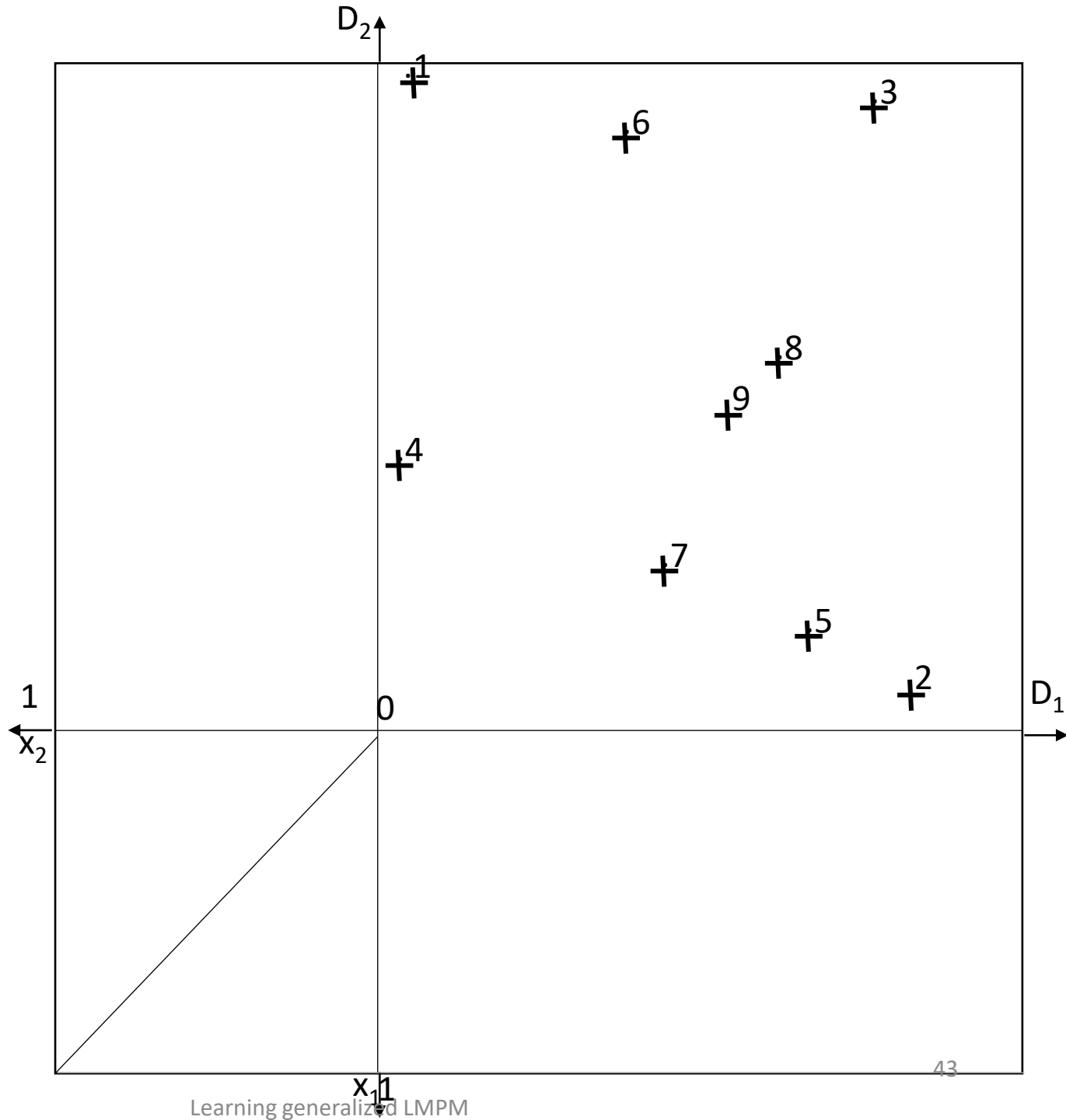
Ex.3 **learn and test**
regular contour lines in
the PC,

Fix attribute
preferences, construct
corresponding images
in DC and chose points
in layers between
contour lines in the DC

Now arbitrary choice of
points in DC layers gives
a learning task

We can try to cheat
some methods

+¹



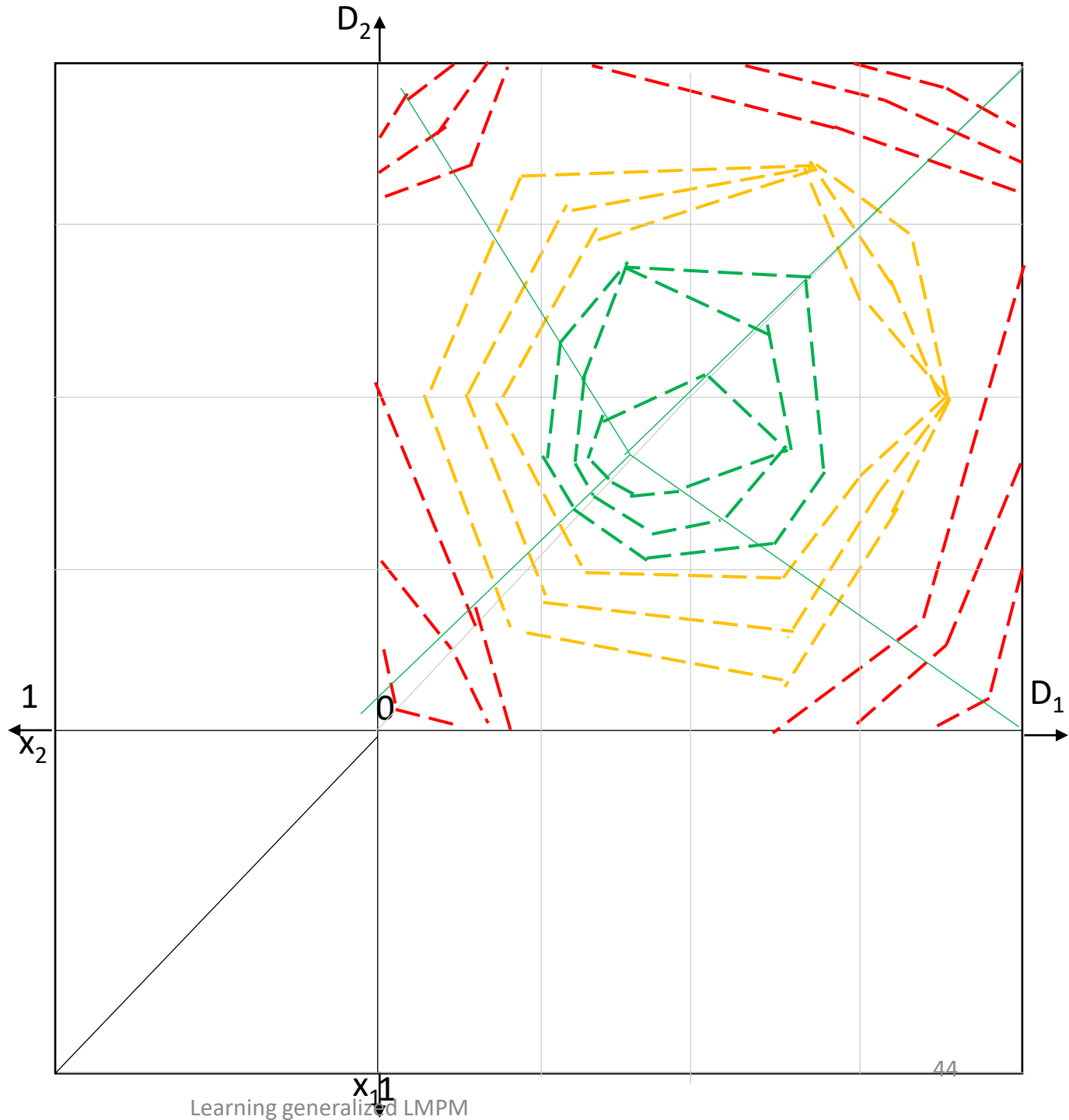
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Ex.3 design contour lines in DC that are not concentric

We can choose arbitrarily points in layers in DC

Here it seems we do not have any Pareto compliance

We must preserve only monotony



learning users so far

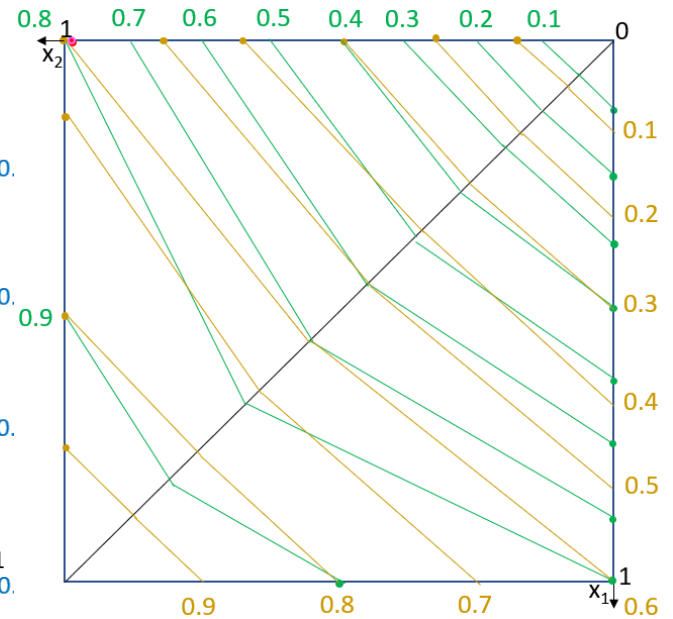
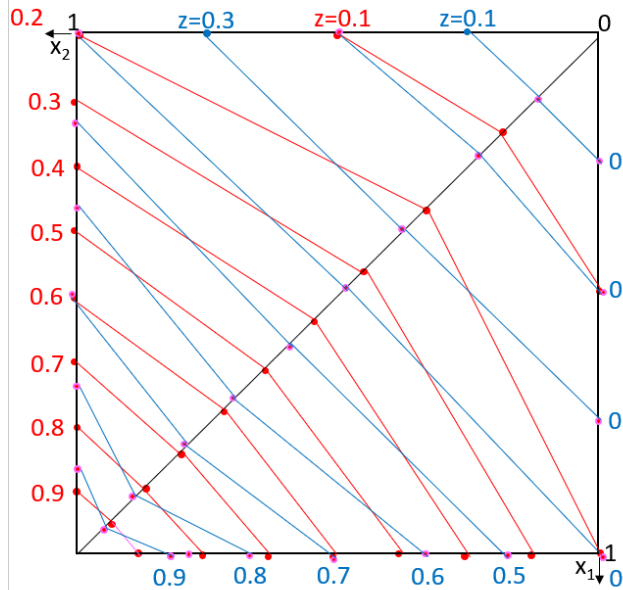
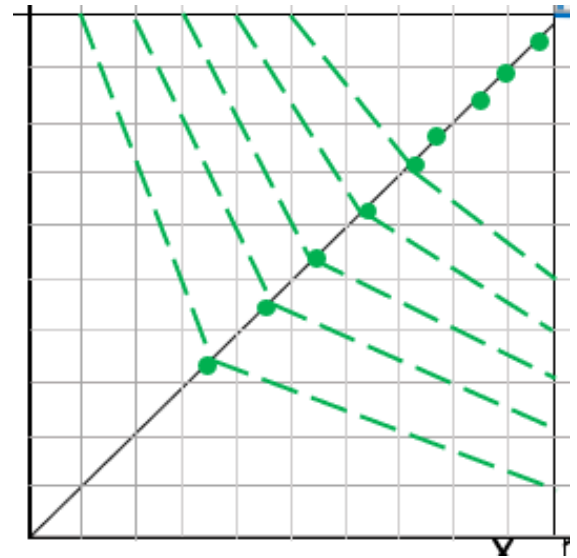
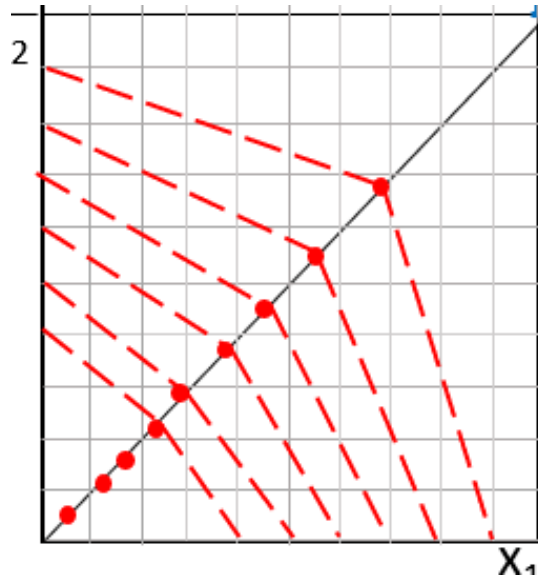
We did not try to learn convex combinations

Learning from data generated by product conjunction and disjunction showed success (partial)

Nevertheless, we have to give up exact behavior on the diagonal

This leads us to a class of connectives where point is on contour line connecting (some) point on the diagonal and respective point on the 0 or 1 axis (of course not violating order and without any intersections of contour lines)

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Experiment 4.

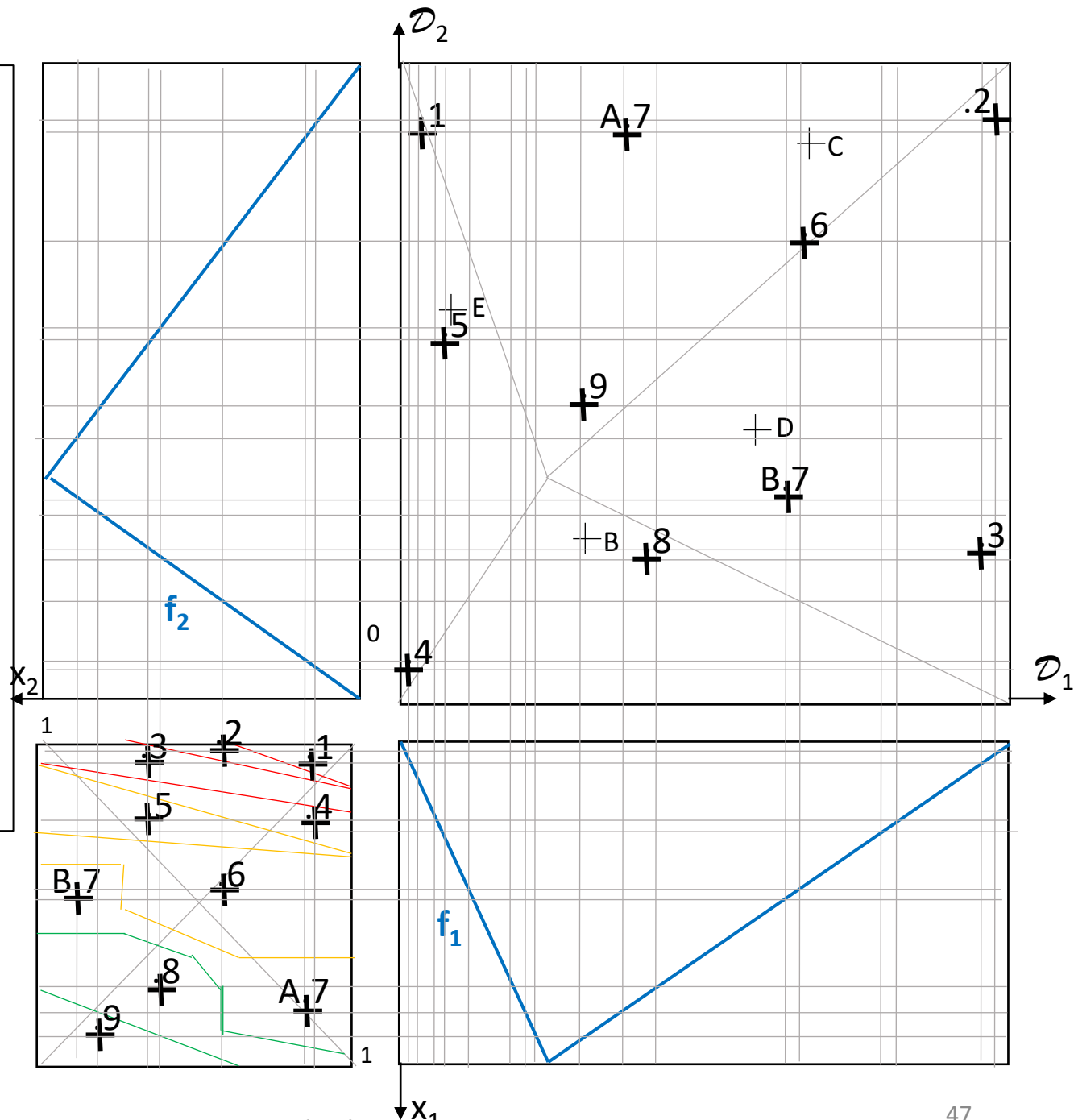
Arbitrary Pareto compliant contour lines

Ex4. Generate

Ex.4 Yet again a new idea
– let's call it "Wild
guess".

It assumes almost
arbitrary borders
between different
preference degrees (z
does not correlate with
intersection of the
diagonal)

Let's chose PC points in
respective layers from
(0,0) to (1,1) point

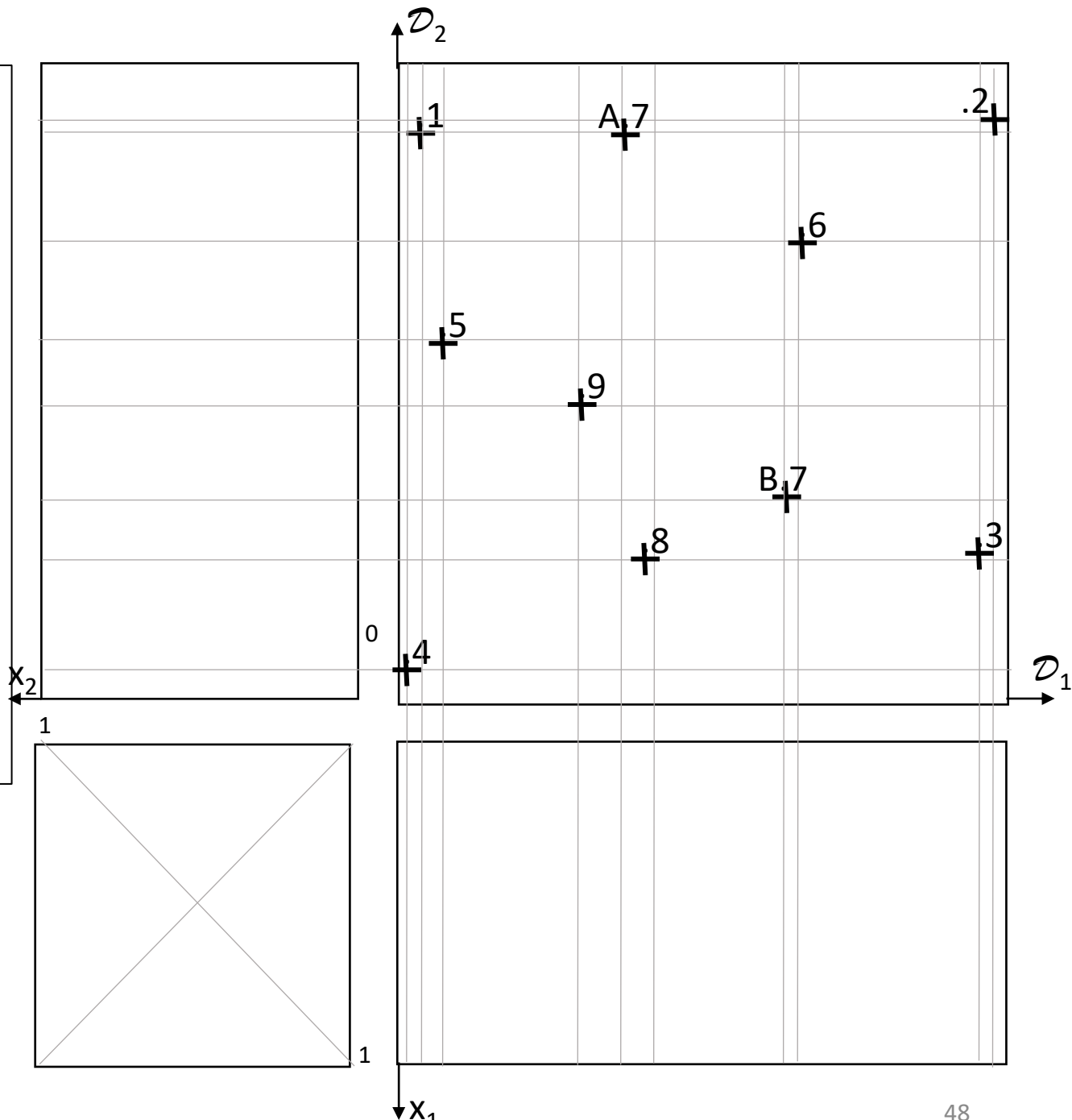


Ex4. Train and test

Ex.4 Yet again a new idea
– let’s call it “Wild guess”.

It assumes almost
arbitrary borders
between different
preference degrees (z
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diagonal)

Let’s chose PC points in
respective layers from
(0,0) to (1,1) point



Randomly generated data

+⁸ ●

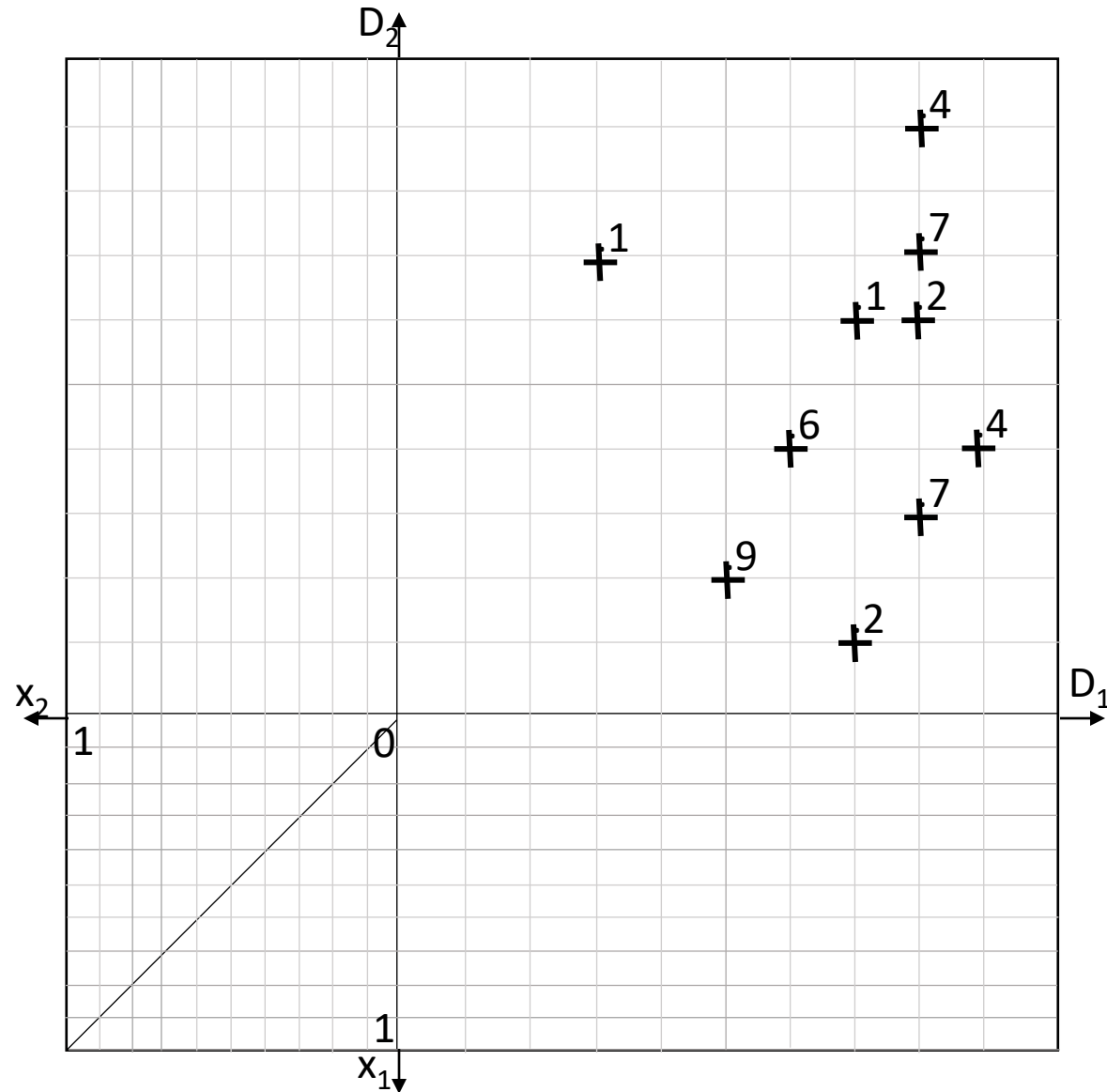
Ex4. Train and test

Ex.4 Yet again a new idea – let's generate randomly data in DC.

For each data point we need 3 numbers between 1 and 9
normalized domains are divided equidistant

(x_1 , x_2 score 0.z)

8	7	7
8	9	4
6	4	6
8	3	7
9	4	4
4	7	1
7	6	1
5	2	9
8	6	2
7	1	2



Randomly generated data

+⁸



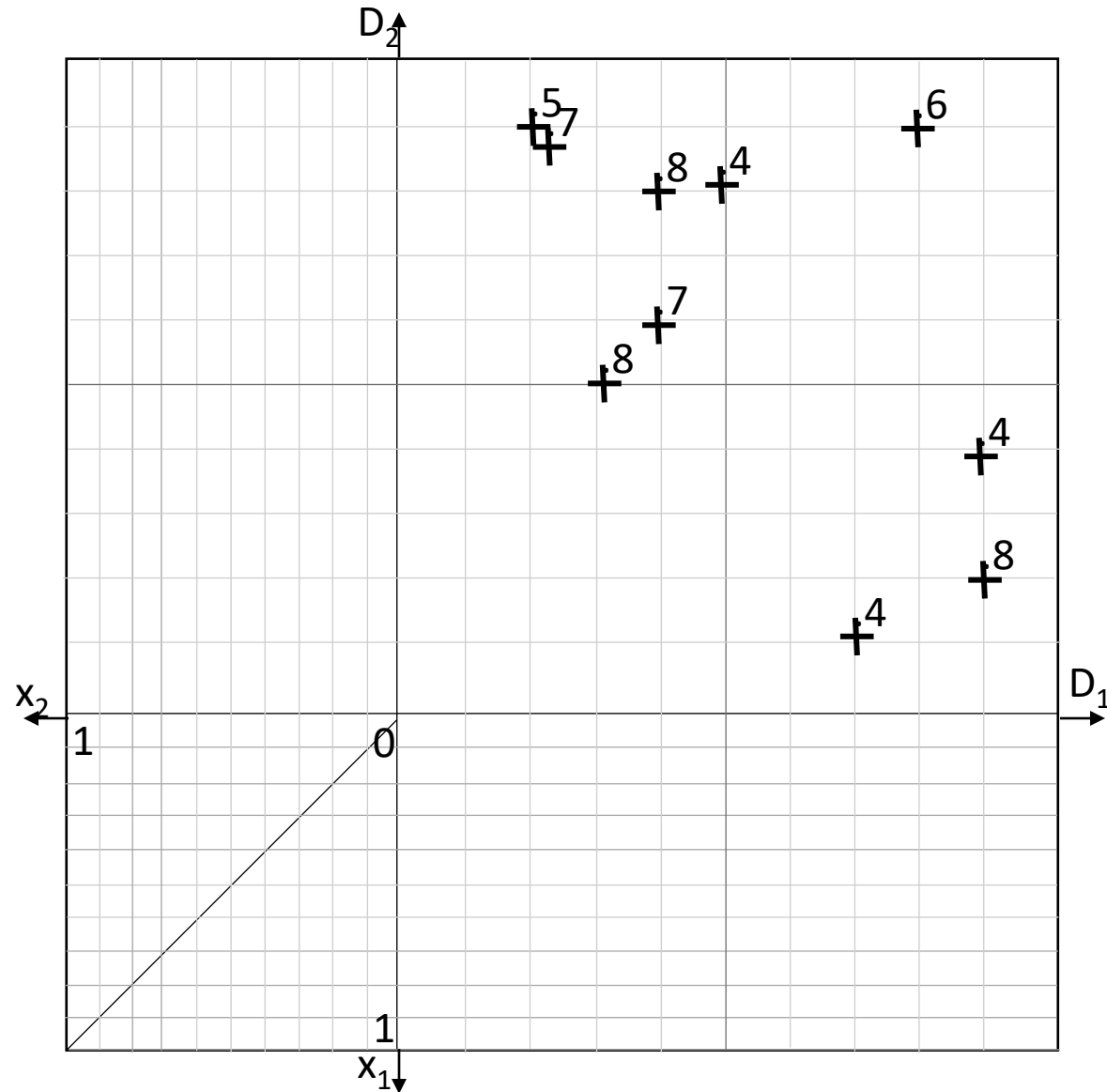
Ex4. Train and test

Ex.4 Yet again a new idea – let's generate randomly data in DC.

For each data point we need 3 numbers between 1 and 9
normalized domains are divided equidistant

(x_1 , x_2 score 0.z)

9	4	4
3	5	8
2	9	5
5	8	4
7	1	4
2	9	7
4	8	8
8	9	6
4	6	7
9	2	8

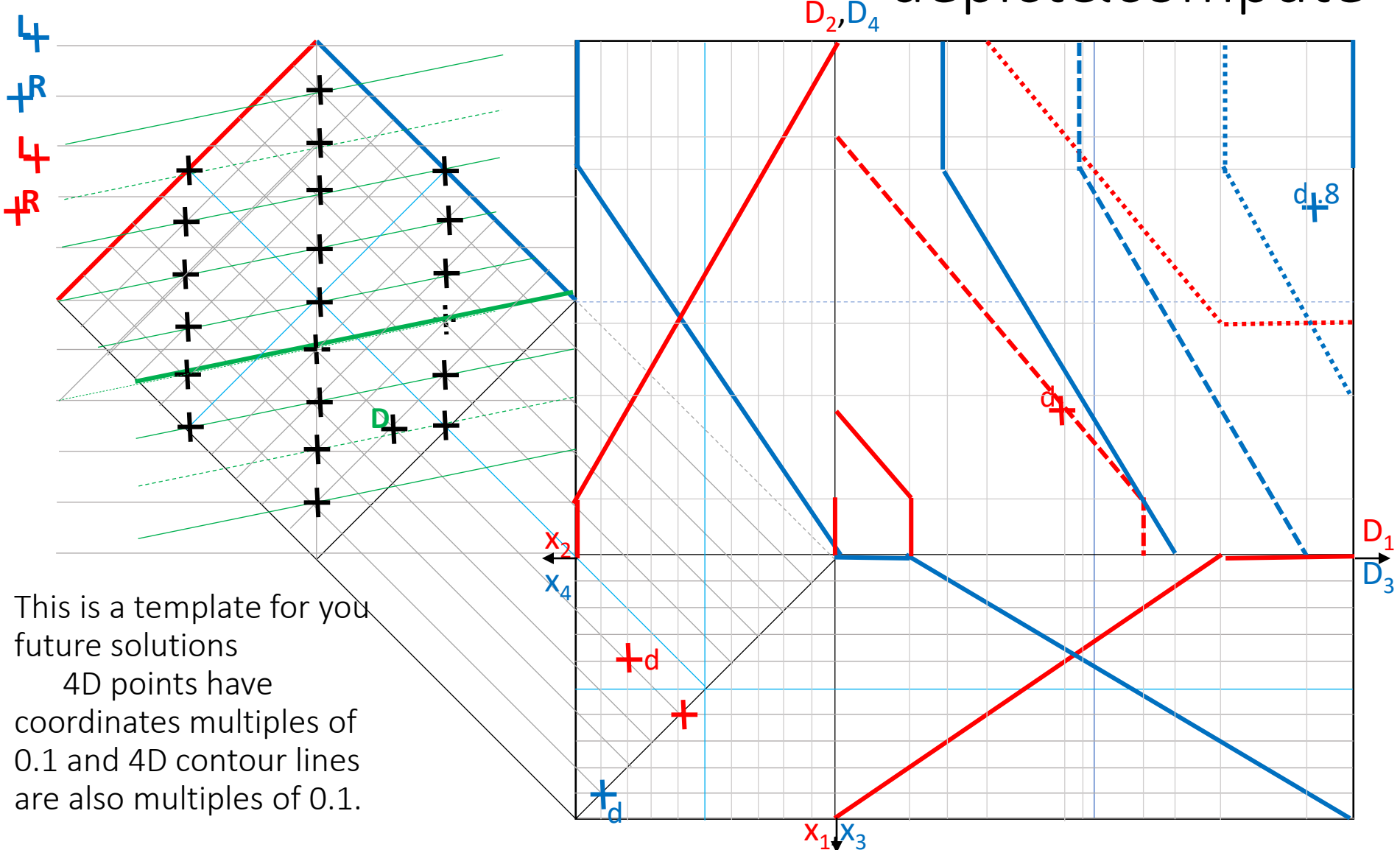


4-D learning?

advantage of visual insight disappeared

$$2 * \frac{x_1 + x_2}{2} + 3 * \frac{2 * x_3 + x_4}{3} = \frac{2 * y_{1,2} + 3 * y_{3,4}}{5} = z$$

4d points easy to depict & compute



This is a template for you future solutions
 4D points have coordinates multiples of 0.1 and 4D contour lines are also multiples of 0.1.

Conclusions

- No libraries, paper work, one should be able to verify results given by a software
- Graphical motivation, data visualization
- Aggregation of partial results (attribute score, several recommenders, ...)
- ChRF challenge response framework as in NSWI166 applies too, we reduce reality to models

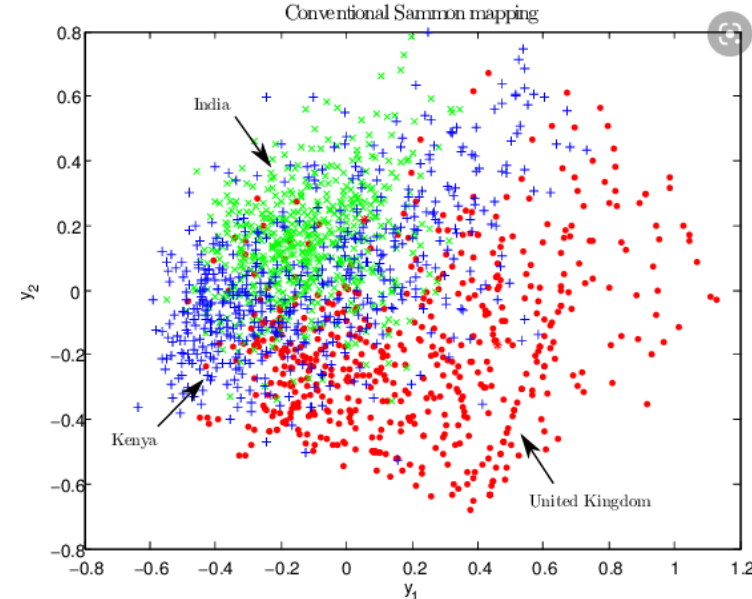
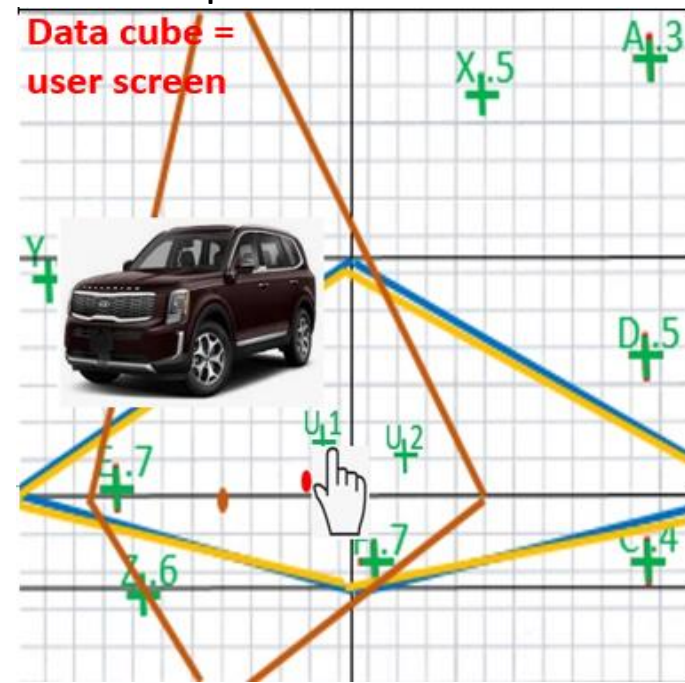


Image is only illustrative
Can we make visualization
compliant with preferences?



Thanks

Questions?

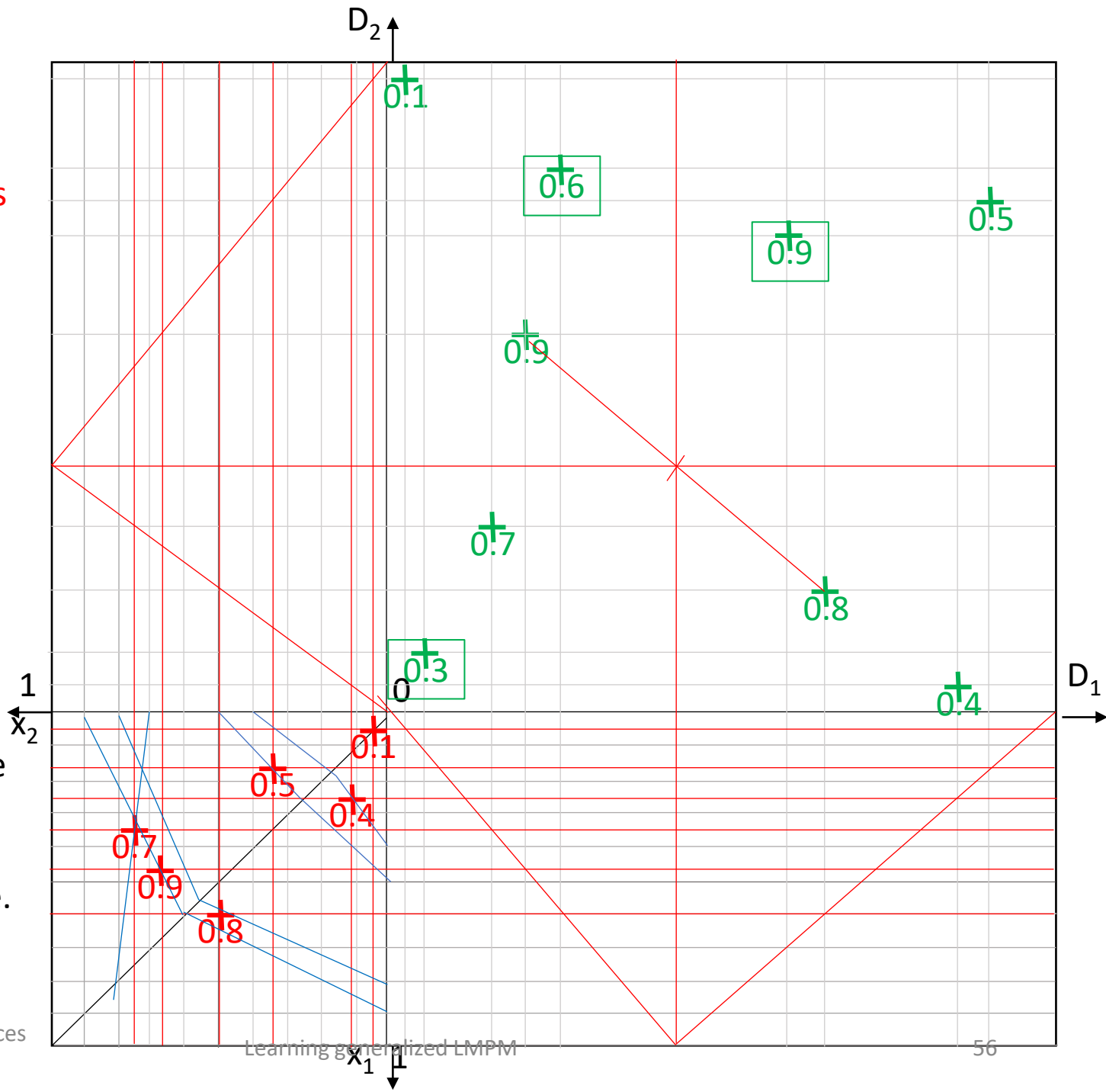
0.3

0.9 0.6

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Ex.2.3 method 3. Approximating missing contour lines

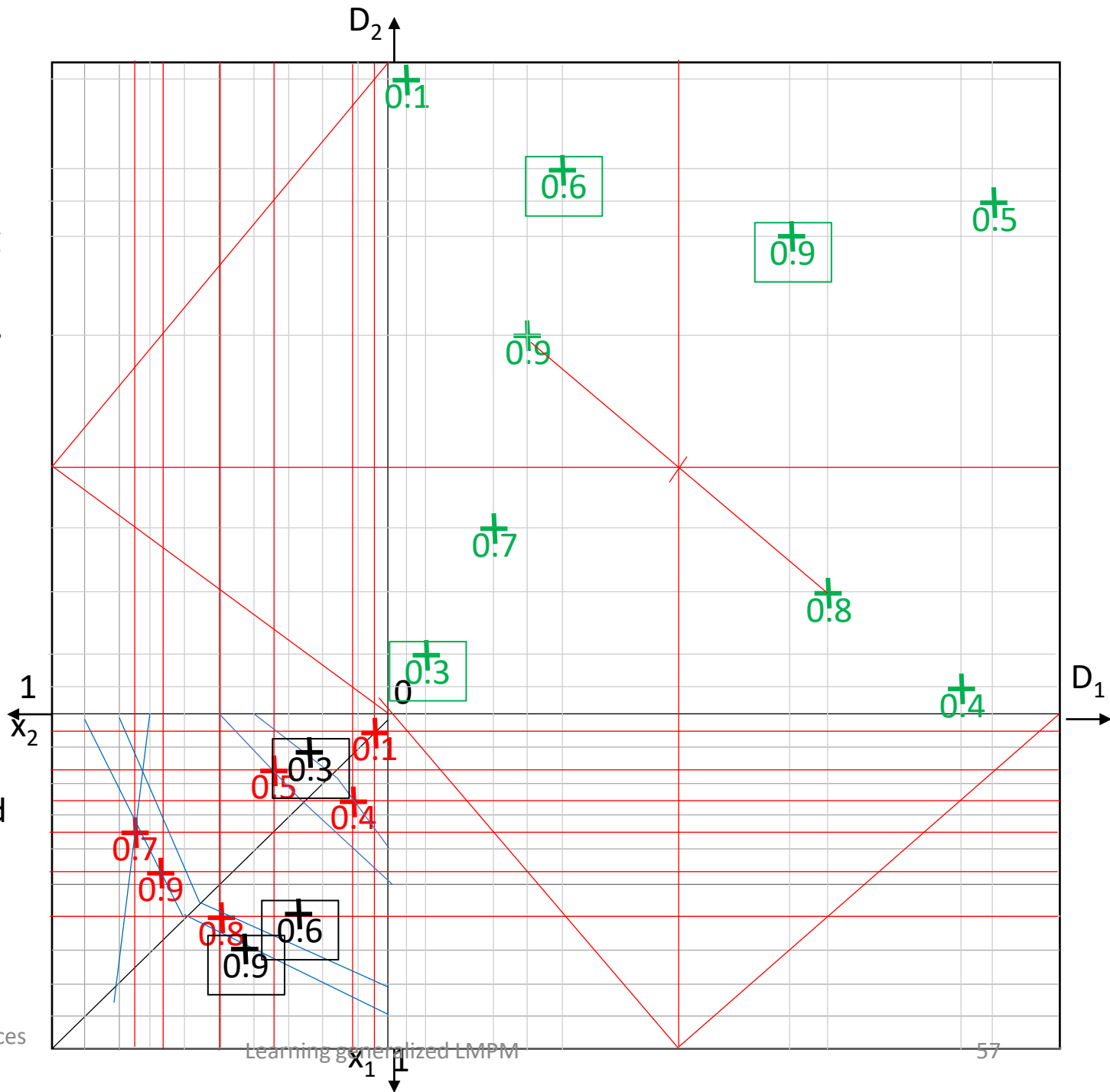
Data, attr. Prefs, training set in PC as before.
Let's try to **find agg. in form of many valued disjunction** – connecting points to known behavior on axis and corresponding intersection with diagonal. Confidence is 5/6 high – there is only one violation with 0.7 contour line. For test set we must approximate corresponding contour lines



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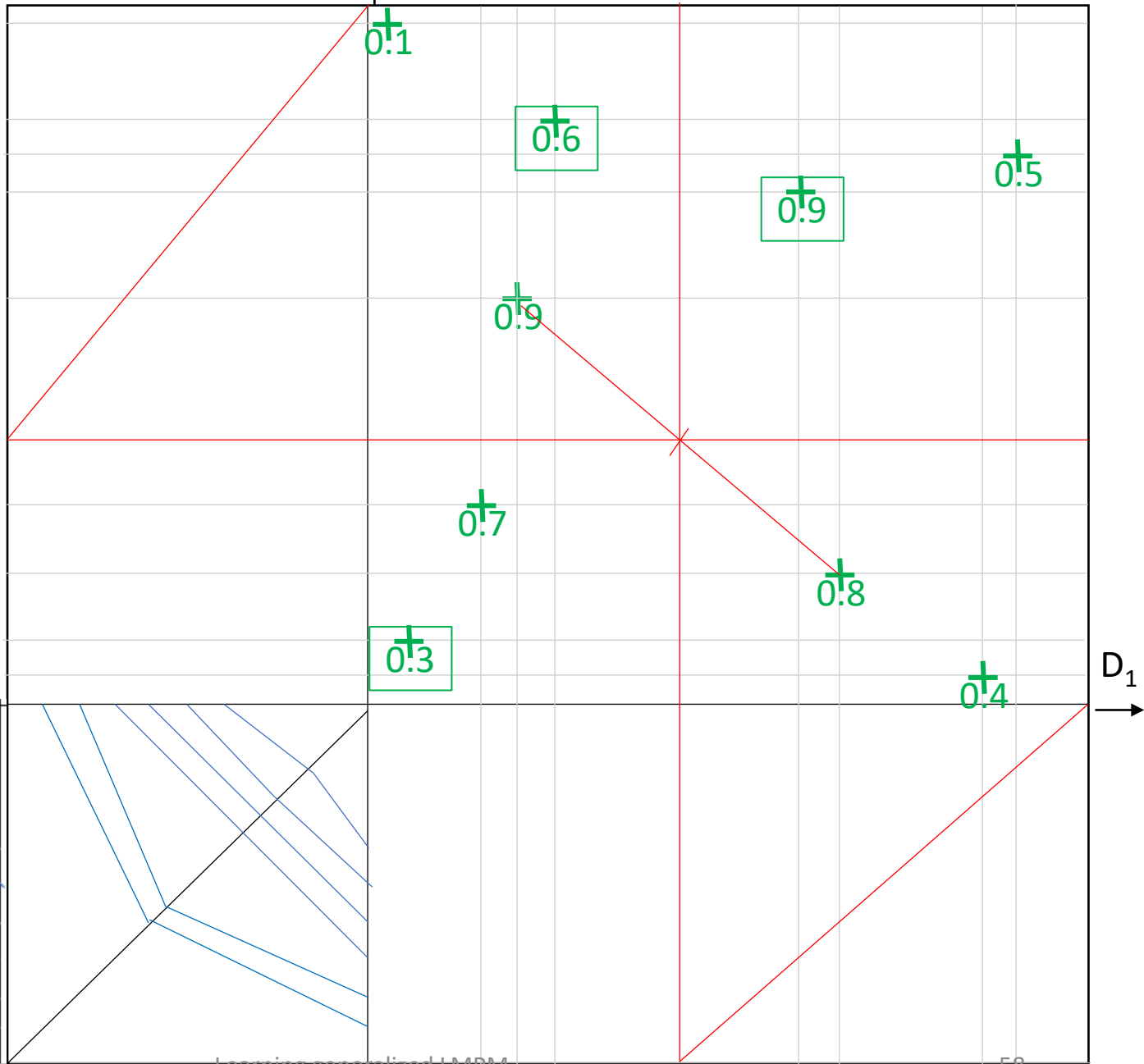
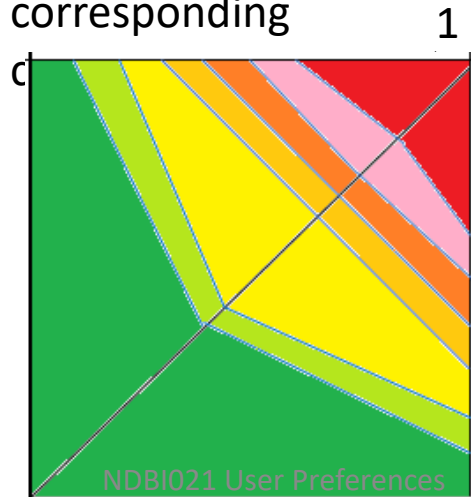
?Ex.2.3 method 3.
error on test set
(calculated to true degree in generating set – here from product disjunction). Confidence 5/6 is rather high. Also order is violated, best 0.7 behind 0.9
For test set we must approximate corresponding contour lines 0.6 and 0.7 in between contour lines 0.5 and 0.8

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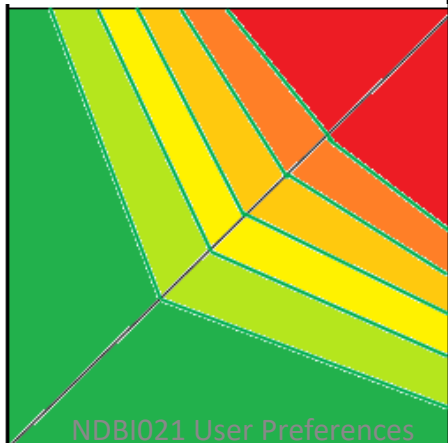
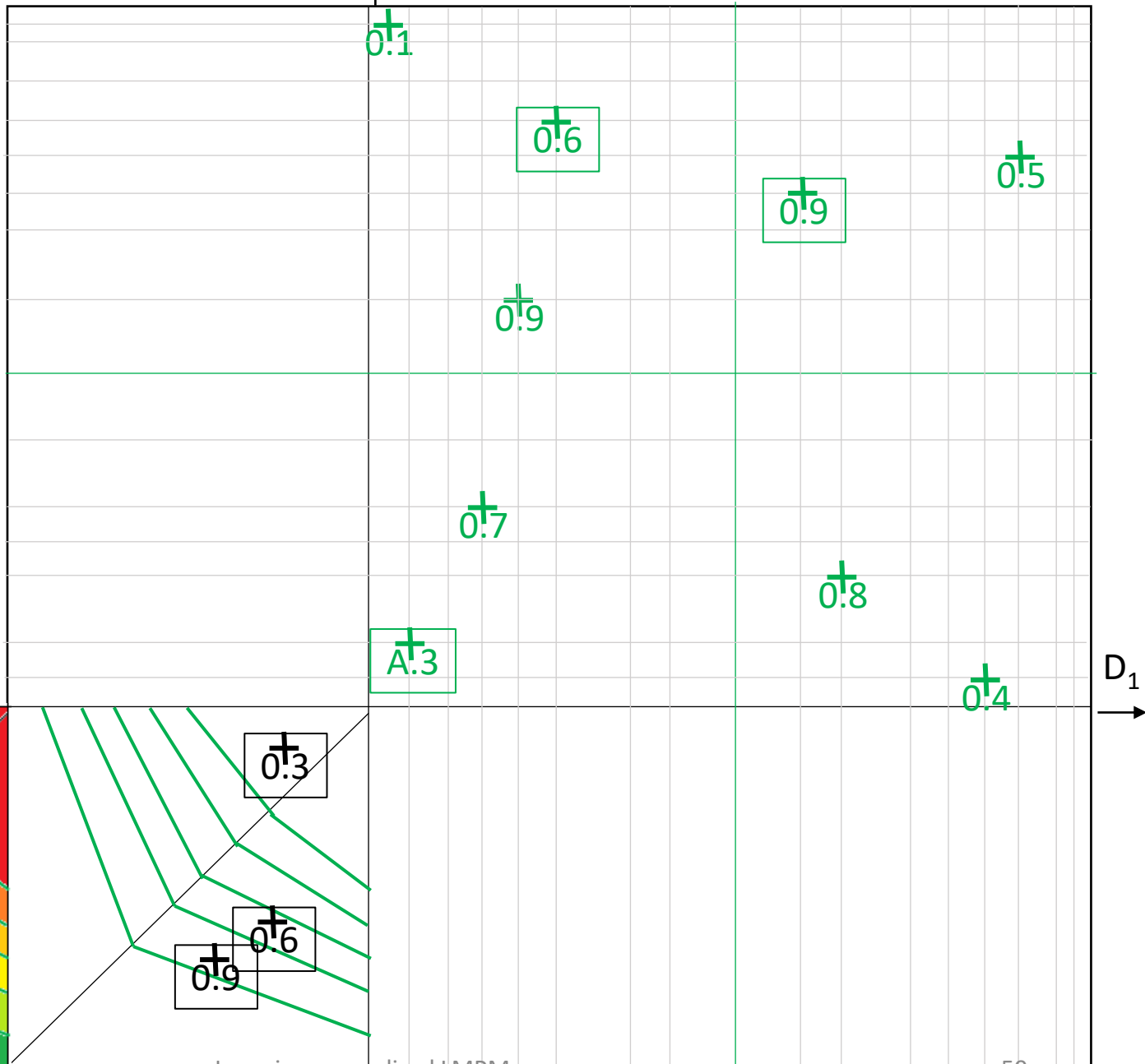
?Ex.2.3 method 3.
error on test set
(calculated to true degree in generating set – here from product disjunction).
Confidence 5/6 is rather high.
Also order is violated, best 0.7 behind 0.9
For test set we must approximate corresponding



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?Ex.2 data
generated by
product logic
disjunction and
attr. Prefs.
We have four
methods

D_2

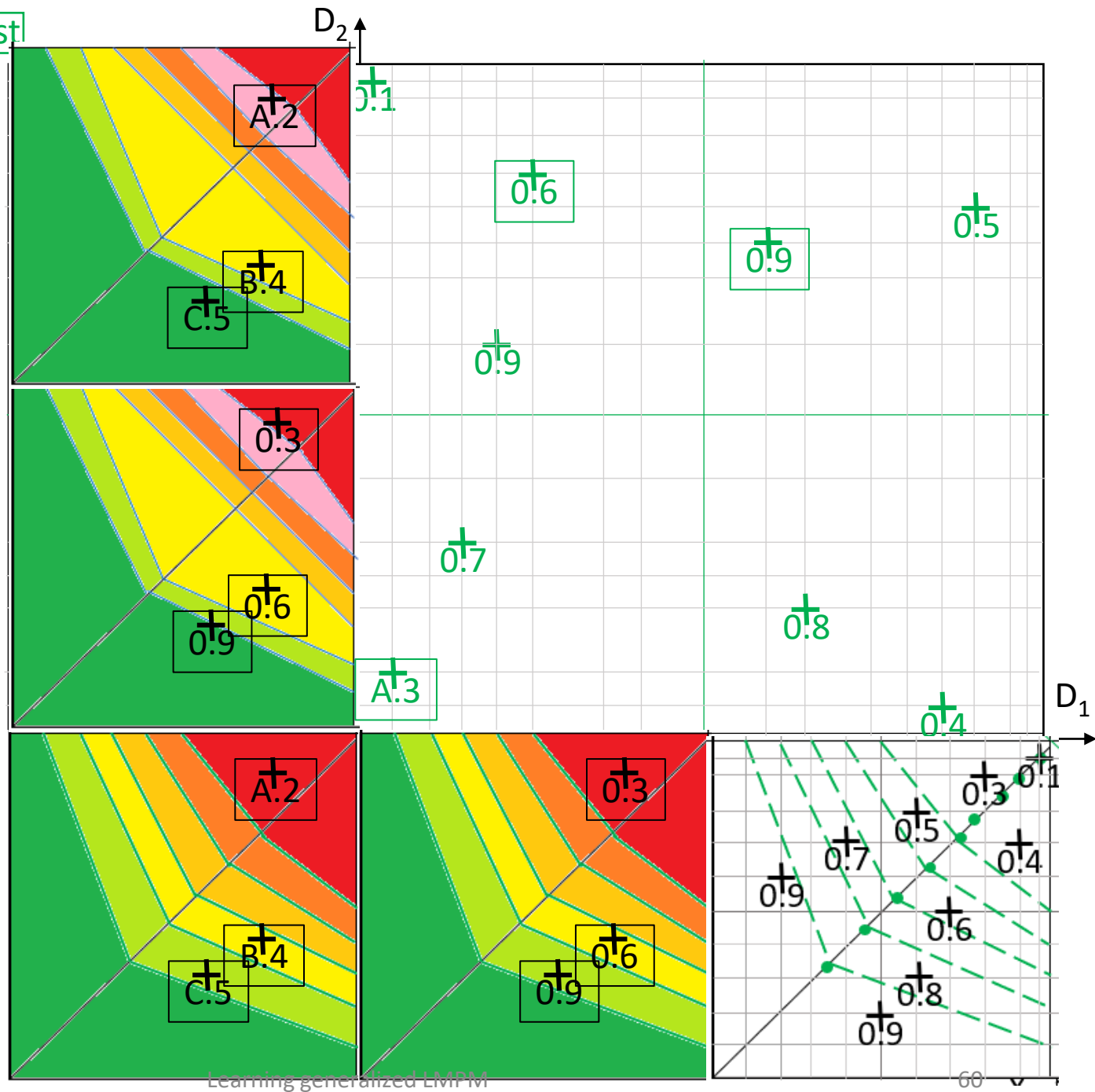


NDBI021 User Preferences

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test

?Ex.2 data
generated by
product logic
disjunction and
attr. Prefs.
We have four
methods



Randomly generated data

