# PRINCIPLES OF DATA ORGANISATION 

R-Tree Greene

## MOTIVATION

(c. How to search effectively in more than one dimension?
© B-tree for multidimensional data $\sim$ R-tree

## R-TREE GRERNE

(2. Greene 1989
@ Modification of the split algorithm of the original R-tree (Guttman)
d. Splitting is based on a hyperplane which defines in which node the objects will fall

## INSERT : SPIITNODE

## SplitNode(P,PP,E)

ChooseAxis(); // choose the hyperplane
Distribute();

## ChooseAxis()

PickSeads; \{ from Guttman's version - returns seeds $\mathrm{E}_{\mathrm{i}}$ and $\mathrm{E}_{\mathrm{j}}$ \}
For every axis compute the distance between MBRs $\mathrm{E}_{\mathrm{i}}, \mathrm{E}_{\mathrm{j}}$;
Normalize the distances by the respective edge length of the bounding rectangle of the original node;
Pick the axis with greatest normalized separation;

## Distribute()

Sort $\mathrm{E}_{\mathrm{i}} \mathrm{s}$ in the chosen axis j based on the j -th coordinate; Add first $\lceil(M+1) / 2\rceil$ records into $P$ and rest of them into PP;

| A | A |  | F | F |  |  | D |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| A | A |  | B | B | B |  |  |
|  |  |  | B | B | B |  |  |
| E | E | E |  |  |  |  |  |
| E | E | E |  |  |  |  |  |
|  |  |  | C | C | C | G |  |
|  | H |  |  |  |  | G |  |
|  | H |  |  |  |  | I | I |

## PickSeeds:

$A$ and $I$ (Guttman): 64-6 $=58$

## ChooseAxis:

Axis X: 4/8
Axis Y: 5/8 ... maximum
Normalization: we have $8 \times 8$, but in case of $8 \times 32$ the distance should be relative to this size

## Distribute:

I, H, G, C and E, B, A, F, D
Note: Or E can bee moved to the other group

