

PRINCIPLES OF DATA ORGANISATION

Linear (Litwin) hashing



MOTIVATION

- Key, pointer pairs ~ index
- Hashed file organization
- Dynamic hashing
 - More records can be added
- Collapsing a trie
- Issue: Fagin's directory had to be doubled



LINEAR HASHING

🔗 Litwin 1980, Enbody & Du 1988

🔗 **Directory-less scheme**

🔗 No need to double the directory

🔗 No level of indirection

🔗 We need a **continuous address space** in the secondary memory

🔗 **Principal idea**

🌸 Avoid doubling of the directory

🌸 Let us add one page after a pre-specified condition

🌸 E.g., overflow or given number of inserts (bucket load factor)

🌸 The space grows **linearly** – one page after another

🌸 If we find ourselves in i -th step/iteration, then after 2^i insertions we get into $i + 1$ iteration



LINEAR HASHING

- Expensive **expansion process** is divided into **stages**
- Stage **d** starts when the number of pages is $s = 2^d$ and ends when the number reaches 2^{d+1}
 - 0. stage = 1 page
 - 1. stage = 2 pages
 - 2. stage = 4 pages
 - ...
 - d** = the number of bits to be used to address all pages in a given stage
 - 0 bits for 1 page
 - 1 bit for 2 pages
 - 2 bits for 4 pages
 - ...
- A (split) **pointer p** is used to point to pages $0 \dots 2^d$
 - The purpose of **p** is to identify the next page to be split

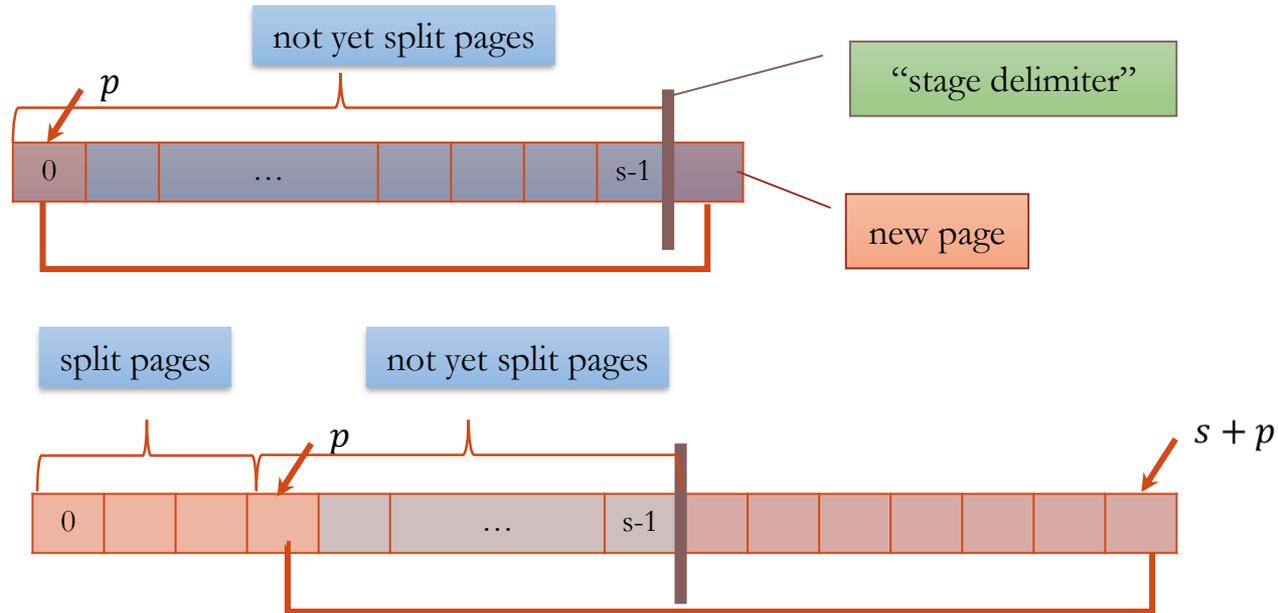


LINEAR HASHING

- At the beginning of stage d , p points to page 0
- After every split operation it is increased by 1 (moves to the next page)
 - If a page overflows before it is its time to split, **overflow pages** need to be utilized
 - The growth of the primary file is linear
- When splitting, the new page will be at position $p+s$
- Records from page p (and overflow pages) will be distributed between p and $p+s$ using $h_{d+1}(k)$
 - We use one more bit to distribute the data
- At each stage we have two types of hash functions
 - for pages already split
 - for pages not yet split
- When we enter a new stage, we move pointer p to the start



LINEAR HASHING – STRUCTURE



EXAMPLE

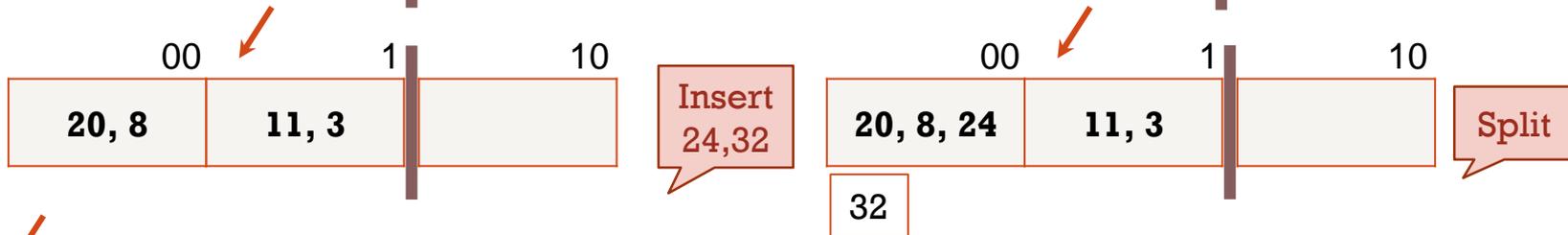
$b = 3$
split: after 2 inserts

20 = 10100
11 = 1011
8 = 1000
3 = 11
24 = 11000
32 = 100000

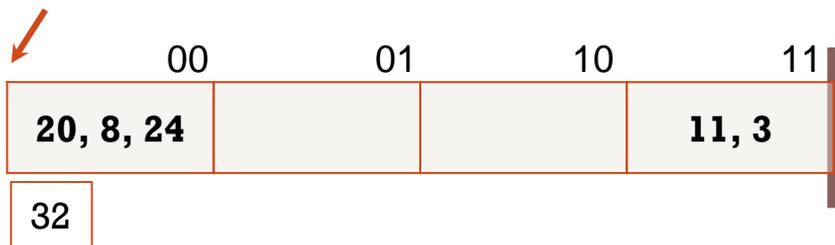
Stage d = 0
 $2^d = 1$ page



Stage 1
 $2^d = 2$ pages



Stage 2
 $2^d = 4$ pages



LINEAR HASHING — ADDRESSING

Unlike directory-based hashing, address of a record has to be computed. Pages left of p are already split and therefore need one more bit for addressing than pages right of p .

```
ADDR GetAddress ( KEY k, int cnt_pages ) {  
    d = floor(log(cnt_pages, 2));  
    s = exp(2, d);  
    p = cnt_pages % s;  
  
    addr = h(k) % s;  
    if (addr < p) addr = h(k) % exp(2, d + 1);  
  
    return addr;  
}
```



LINEAR HASHING — SPLITTING

Uncontrolled splitting

- 🔗 Page pointed to by p is split after a given number of insertions
- 🔗 Page pointed to by p is split when any page overflows

Controlled splitting

- 🔗 Splitting occurs when the utilization of page pointed to by p reaches a threshold, e.g. 80%



OVERFLOW HANDLING POLICY

🔗 Problem: some pages may overflow, but we split some other page

🔗 Overflow handling:

- 🌸 One global overflow area
- 🌸 One overflow page for each page
- 🌸 One buddy page for each page

